


# Monte-Carlo tree search for multi-player, no-limit Texas hold'em poker



Guy Van den Broeck



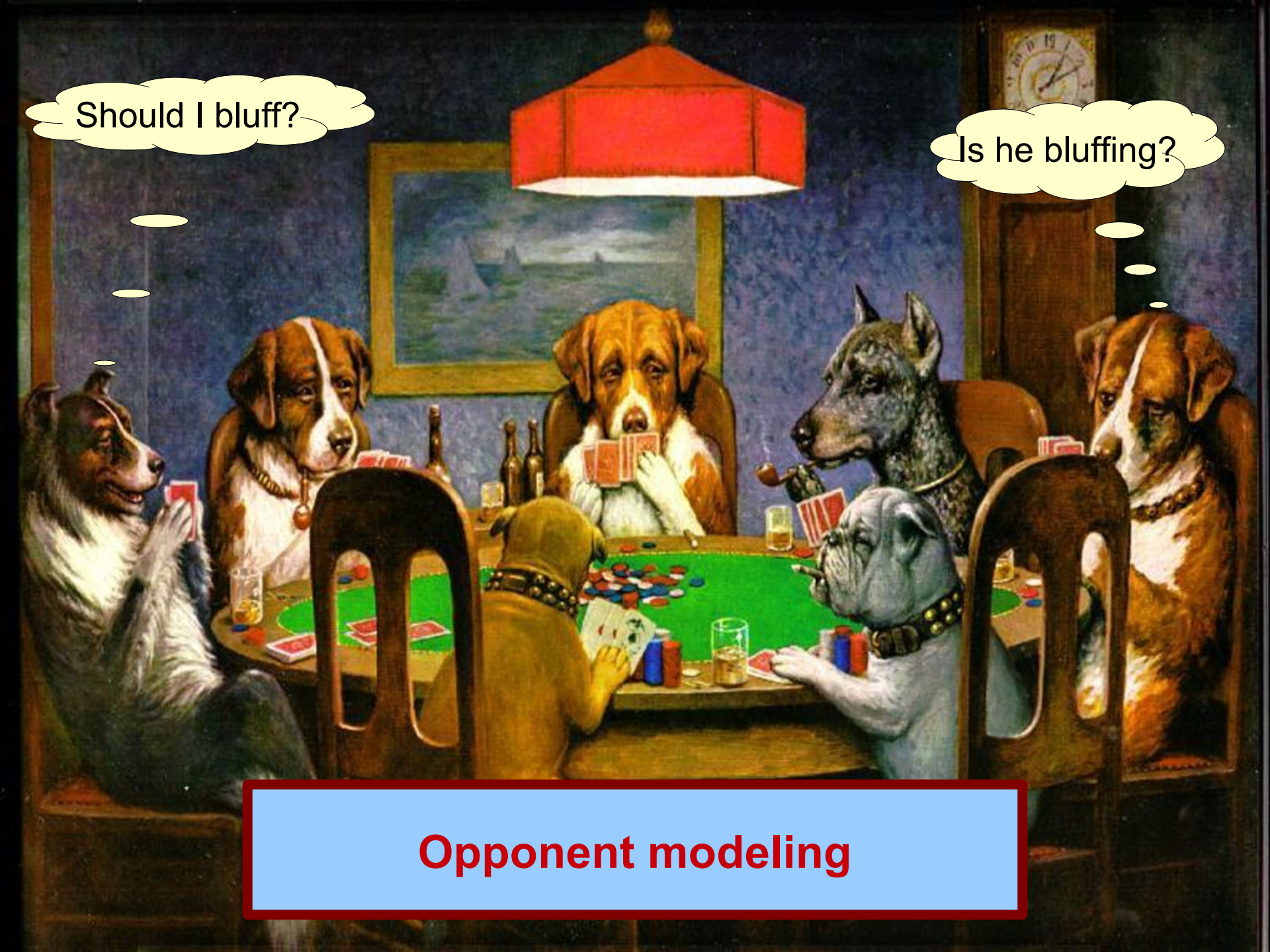


A detailed oil painting depicting six anthropomorphic dogs playing a card game at a round table. The scene is set in a dimly lit room with a red lamp hanging over the table and a clock on the wall. The dogs are of various breeds, including a Sheltie, two Weimaraners, a German Shepherd, and a Bulldog. They are holding cards and chips, and one dog is smoking a pipe. A thought bubble above the Sheltie on the left contains the text "Should I bluff?".

Should I bluff?

**Deceptive play**




A painting of six dogs playing poker at a table. The scene is set in a dimly lit room with a red lamp hanging over the table. The dogs are of various breeds, including a Shetland Sheepdog, a Saint Bernard, a Weimaraner, a Bulldog, and two other breeds. They are all looking at their cards or the table. The table is covered with a green cloth and has various items on it, including cards, chips, and bottles. The background features a framed picture of a landscape and a clock on the wall.

Should I bluff?

Is he bluffing?

**Opponent modeling**



A painting of six dogs playing cards at a table. The scene is set in a dimly lit room with a red lamp hanging over the table. The dogs are of various breeds, including a Shetland Sheepdog, a Saint Bernard, a Weimaraner, a Bulldog, and two other breeds. They are all looking at their cards or the table. The table is covered with a green cloth and has various items on it, including cards, chips, and bottles. The background features a painting on the wall and a clock on the right.


Should I bluff?

Is he bluffing?

Who has the Ace?

**Incomplete information**



A painting of six dogs playing cards at a table. The dogs are a Sheltie, two Weimaraners, a German Shepherd, and a bulldog. They are sitting around a green felt table with cards and chips. A red lamp hangs above them. A clock is on the wall. Thought bubbles are above the dogs. A blue box with red text is at the bottom.

Should I bluff?


Is he bluffing?

Who has the Ace?

What are the odds?

**Game of chance**





Should I bluff?

Is he bluffing?


Who has the Ace?

What are the odds?

I'll bet because he always calls

**Exploitation**





Should I bluff?

Is he bluffing?

Who has the Ace?


What are the odds?

I'll bet because he always calls

What can happen next?

**Huge state space**





Should I bluff?

Should I bet \$5 or \$10?

Is he bluffing?

Who has the Ace?


What are the odds?

I'll bet because he always calls

What can happen next?

**Risk management &  
Continuous action space**





Should I bluff?

Should I bet \$5 or \$10?

Is he bluffing?

Who has the Ace?

What are the odds?

I'll bet because he always calls

What can happen next?

**Take-Away Message:  
We can solve all these problems!**



# Problem Statement



- ! A bot for Texas hold'em poker
  - ! No-Limit &  $> 2$  players
    - ! Not done before!
  - ! Exploitative, not game theoretic
    - ! Game tree search + Opponent modeling
- ! Applies to any problem with either
  - ! incomplete information
  - ! non-determinism
  - ! continuous actions



# Outline



- ! Overview approach
  - ! The Poker game tree
  - ! Opponent model
  - ! Monte-Carlo tree search
- ! Research challenges
  - ! Search
  - ! Opponent model
- ! Conclusion



# Outline



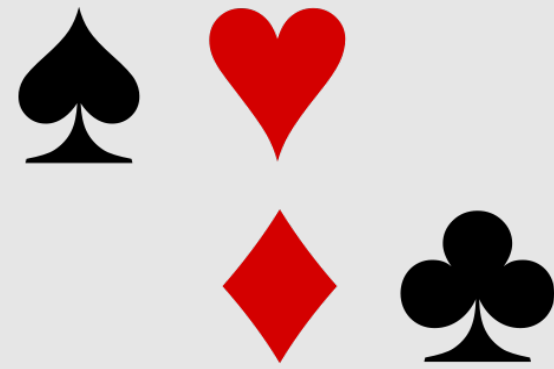
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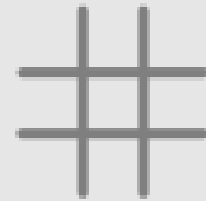
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# Poker Game Tree

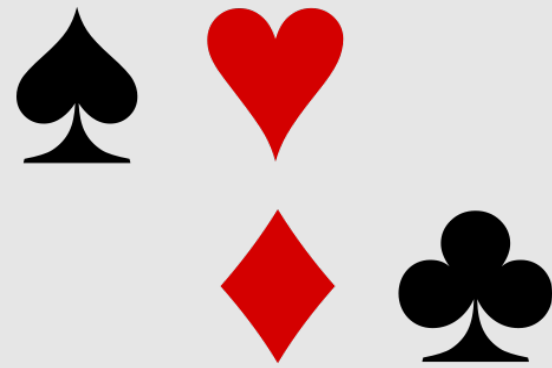
- ! Minimax trees: deterministic
  - ! Tic-tac-toe, checkers, chess, go,...



*max*

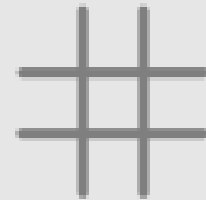
*min*

# Poker Game Tree



! Minimax trees: deterministic

! Tic-tac-toe, checkers, chess, go,...



*max*

*min*

! Expecti(mini)max trees: chance

! Backgammon, ...

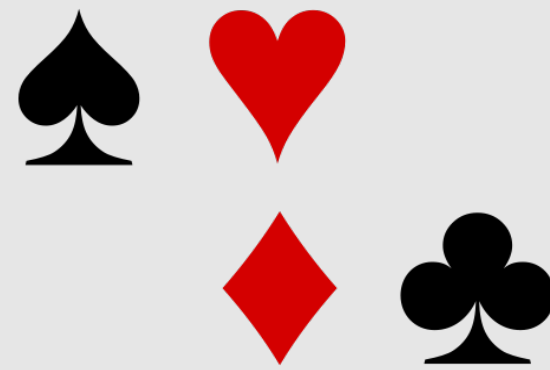


*max*

*min*

*mix*

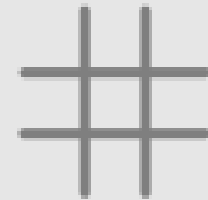




# Poker Game Tree

! Minimax trees: deterministic

! Tic-tac-toe, checkers, chess, go,...



*max*

*min*

! Expecti(mini)max trees: chance

! Backgammon, ...



*max*

*min*

*mix*

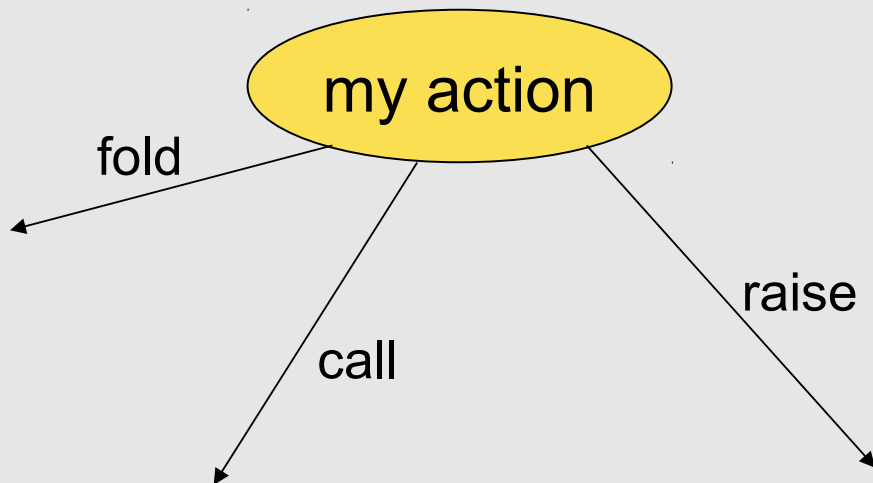
! Miximax trees: hidden information

*max*

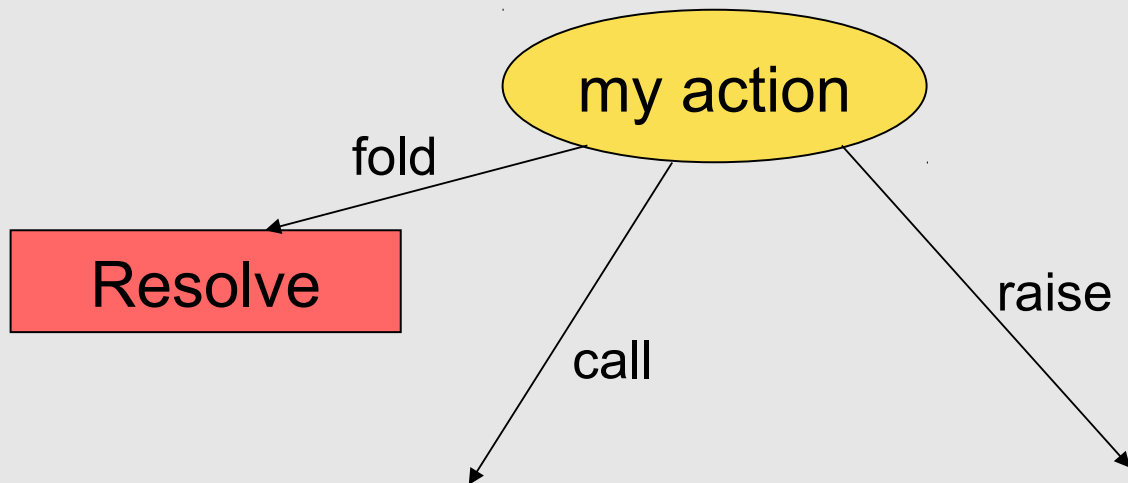
*mix*

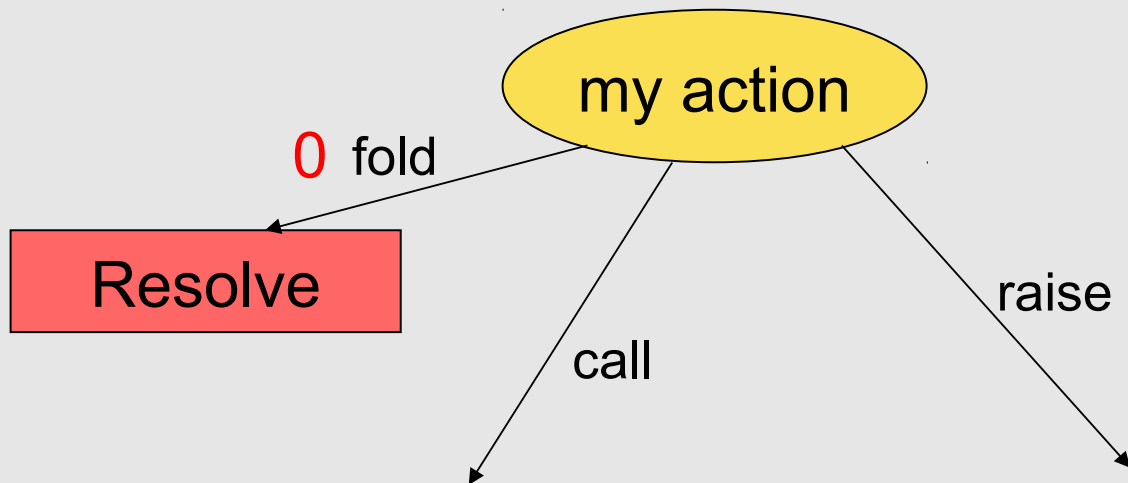
*mix*

+ opponent model

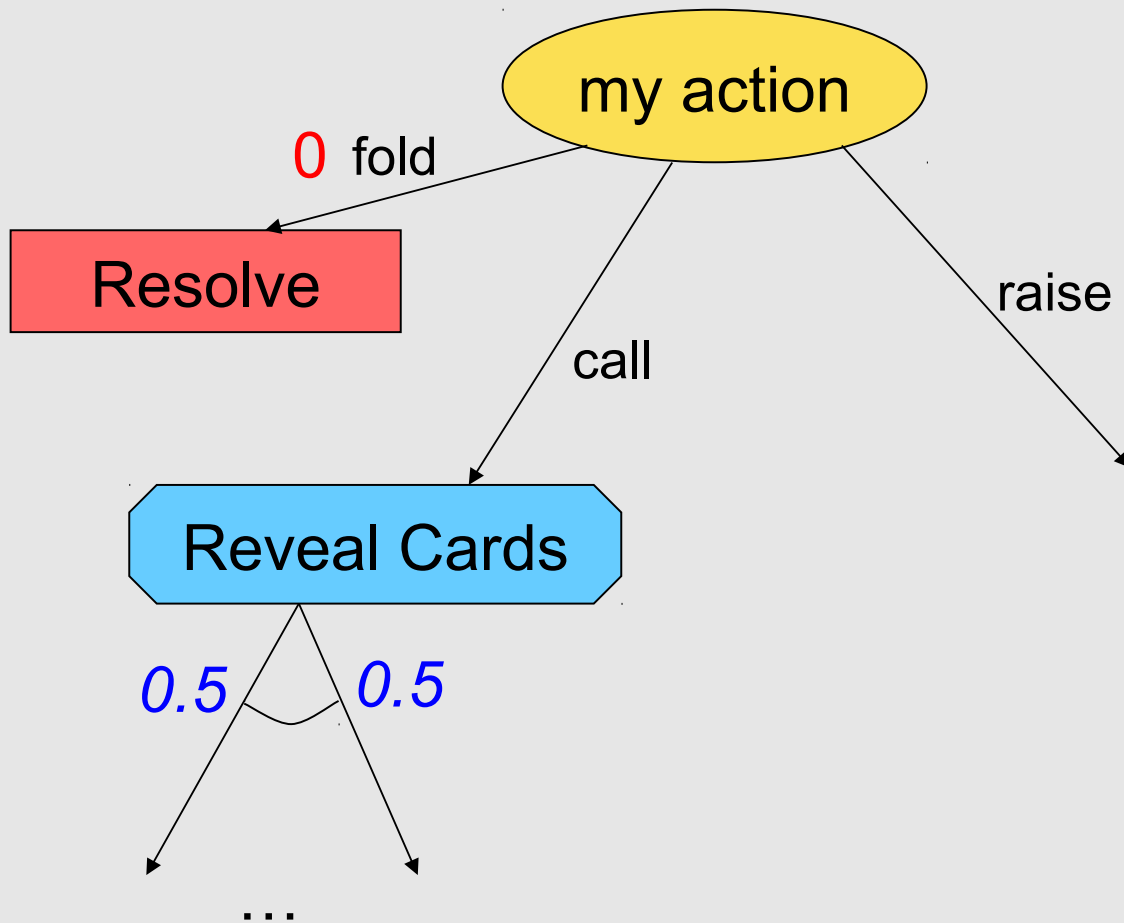


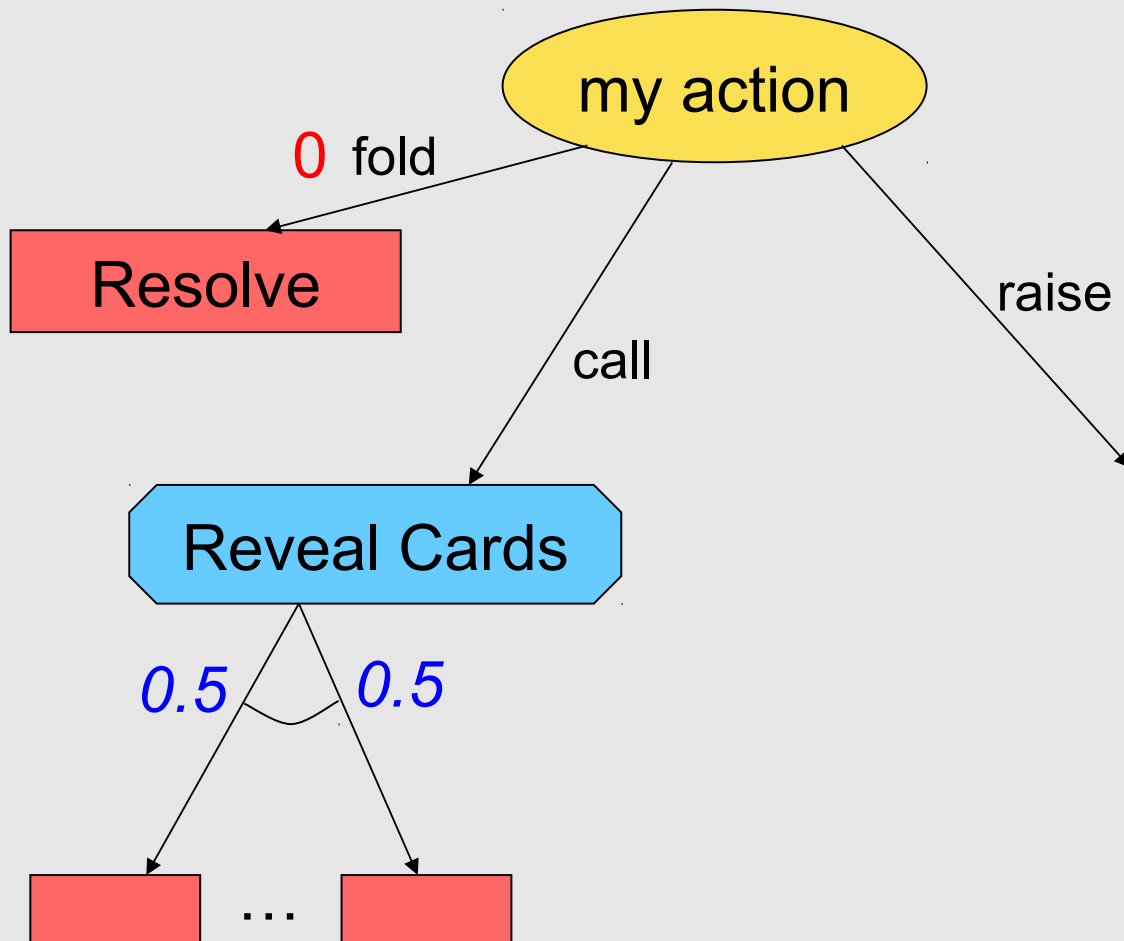




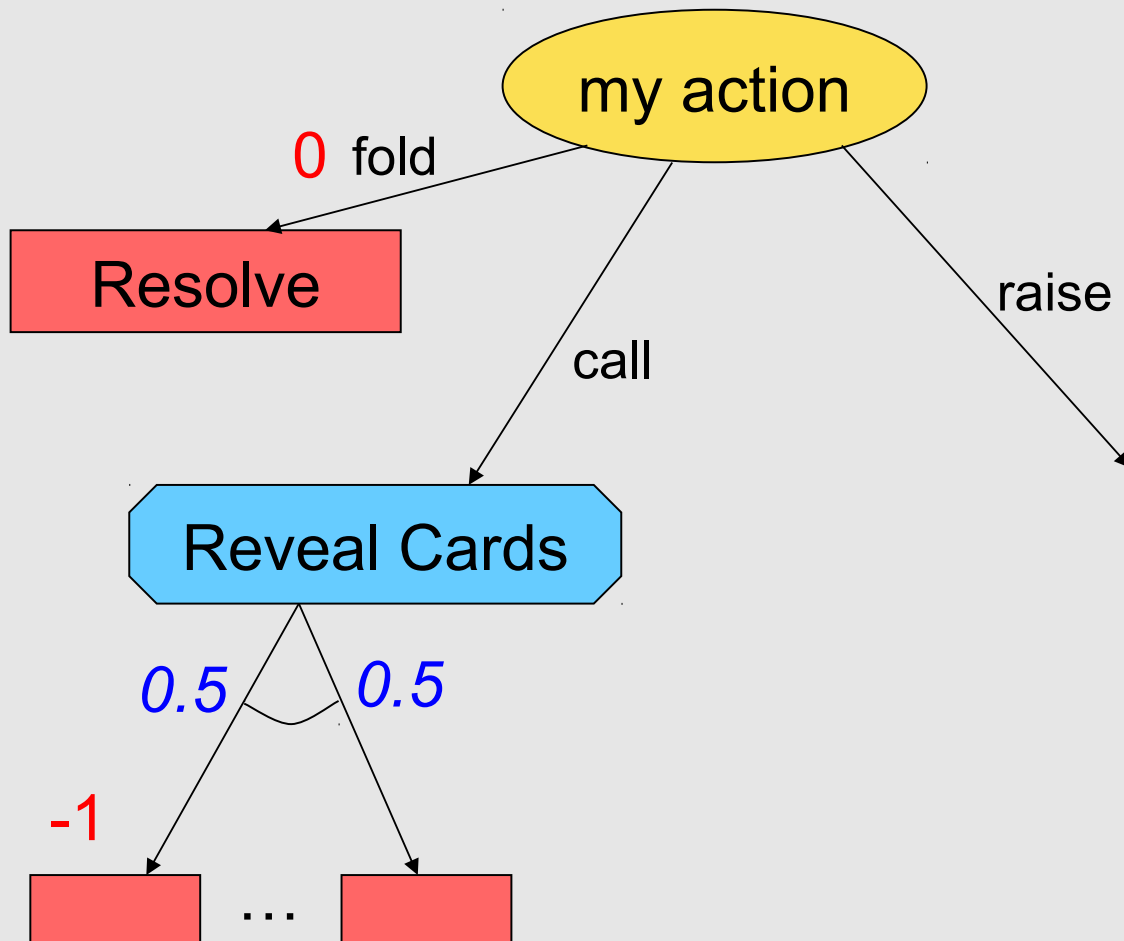


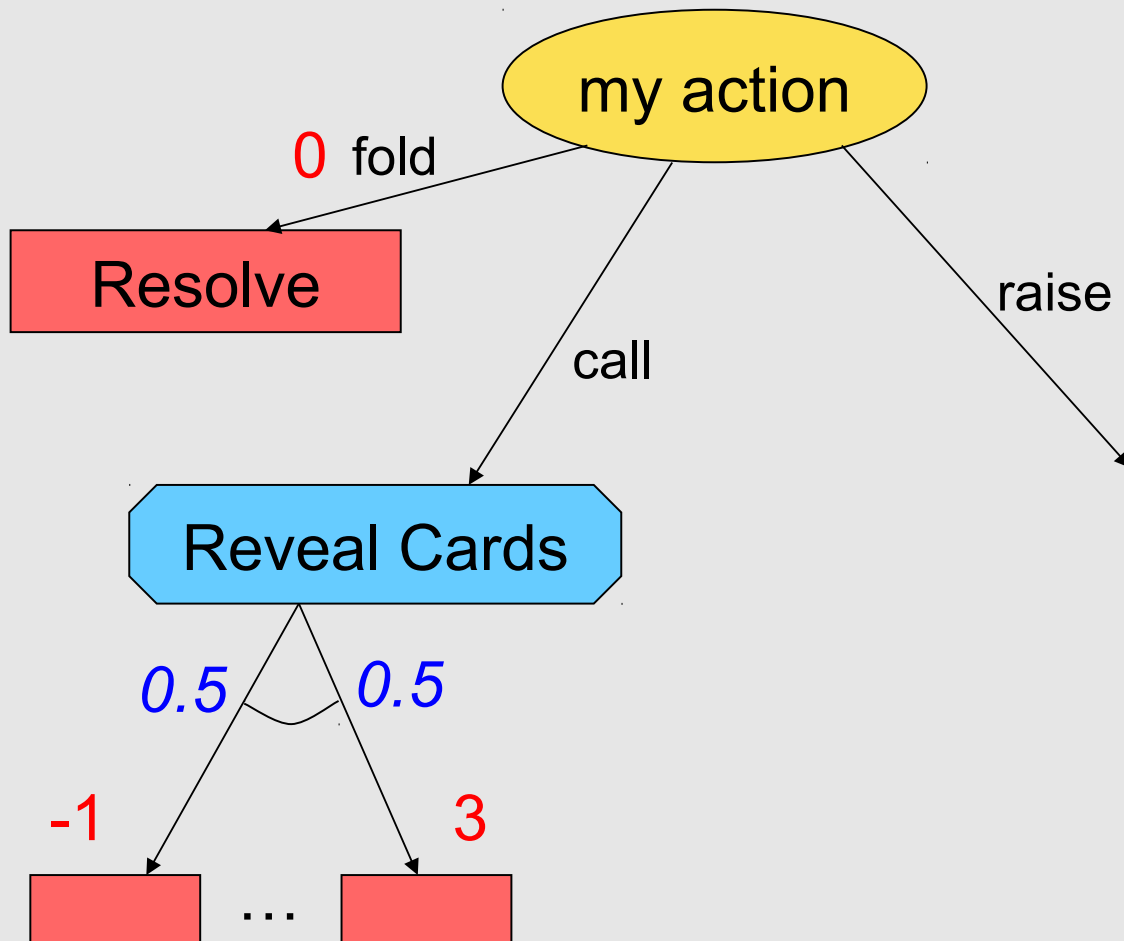




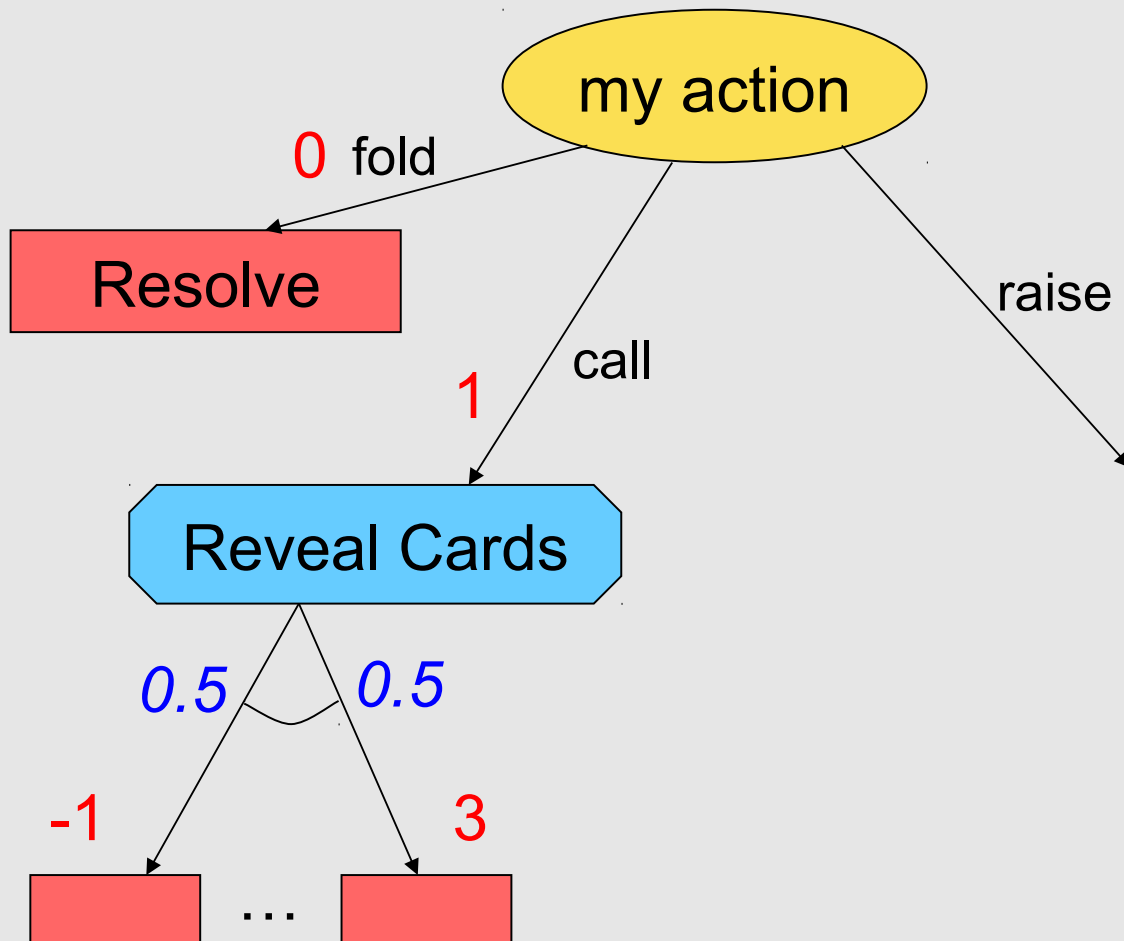


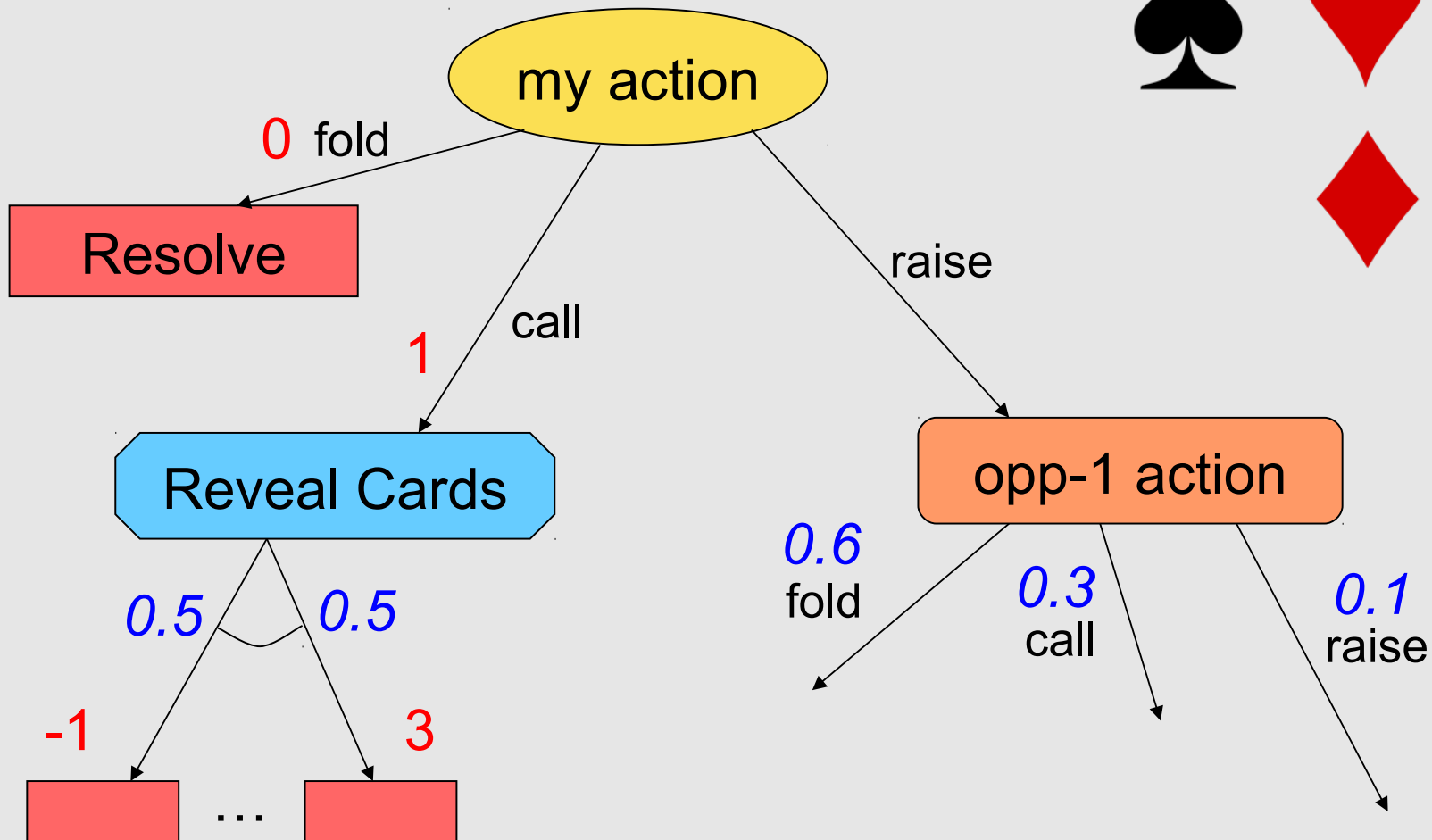


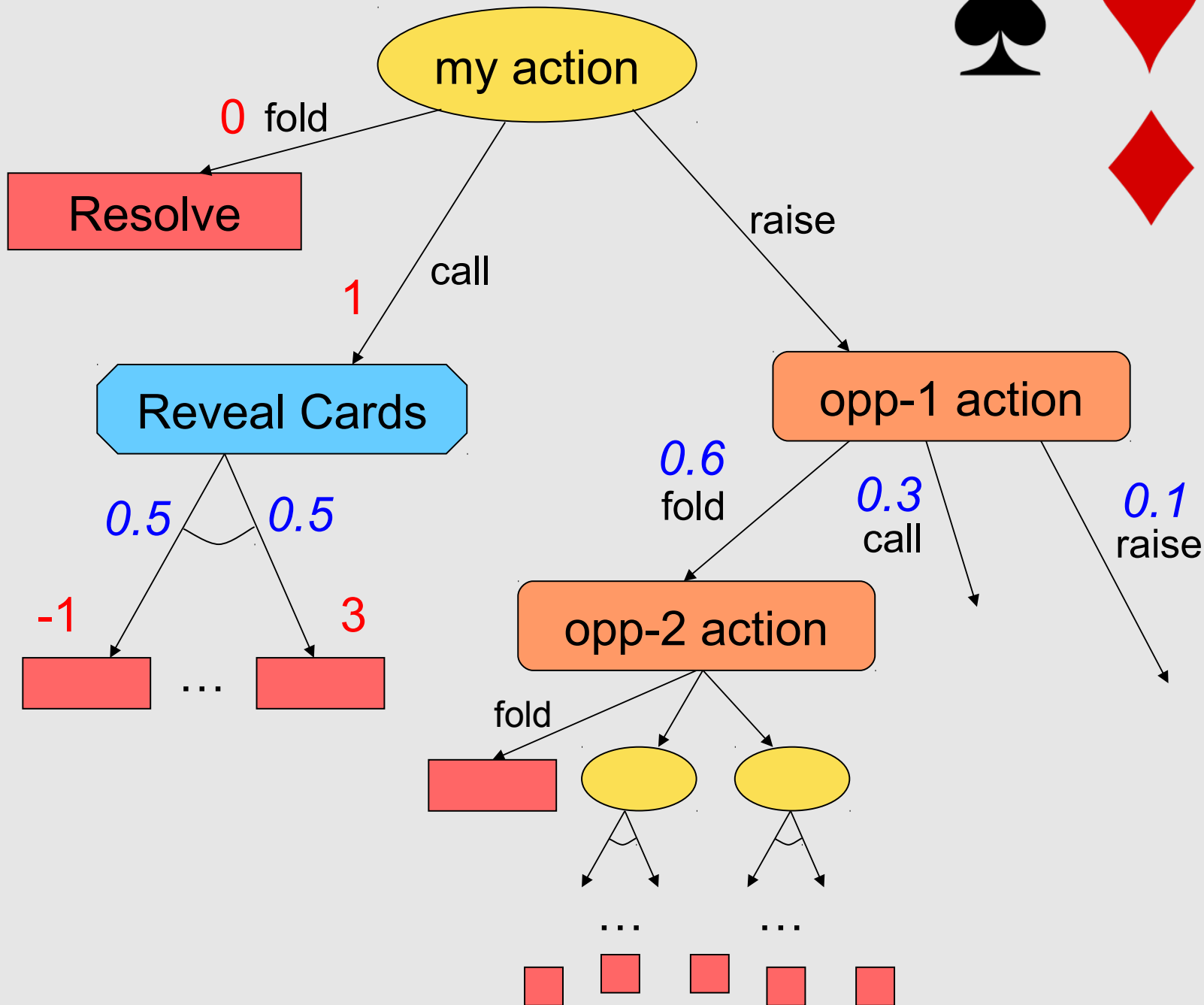




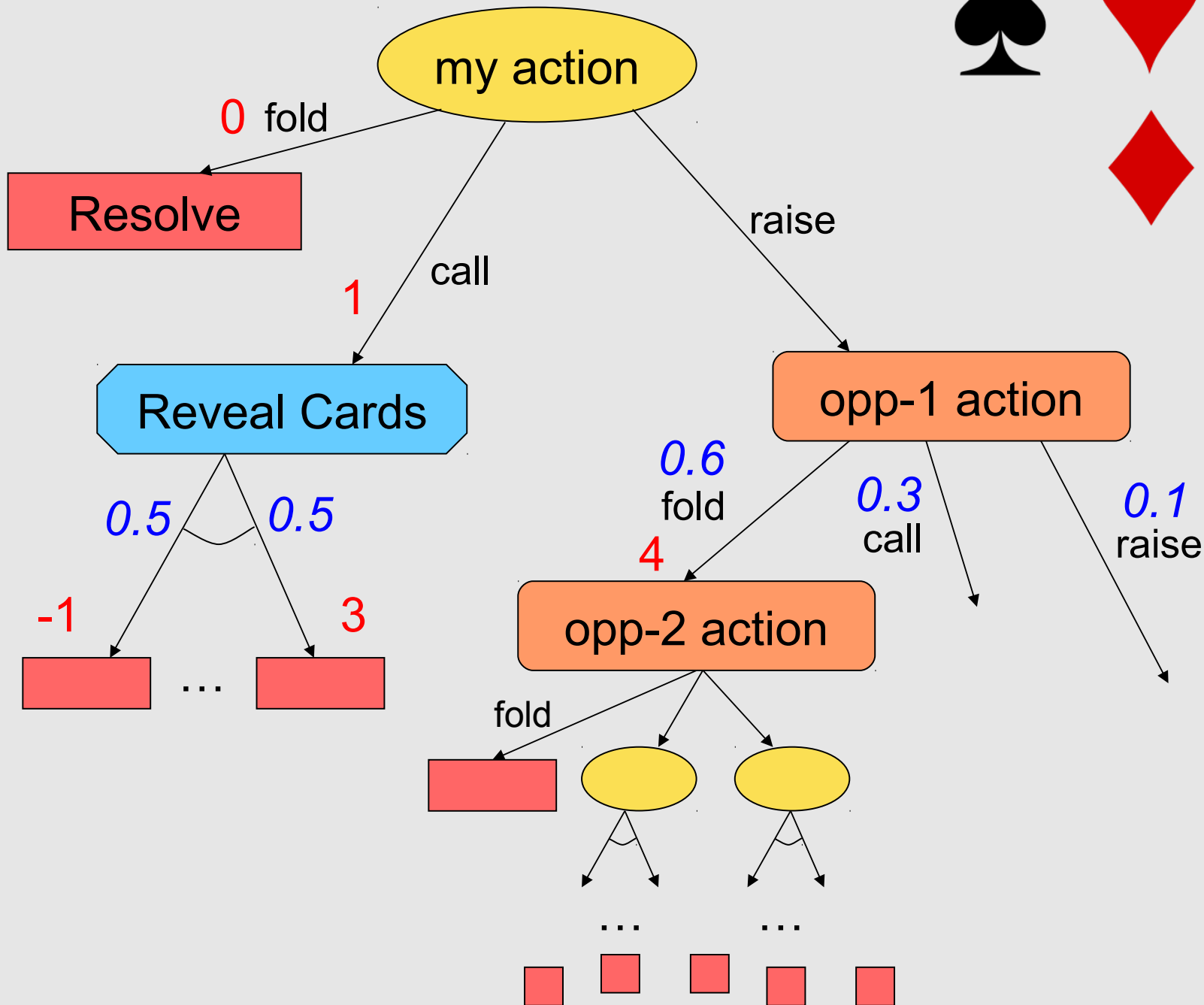


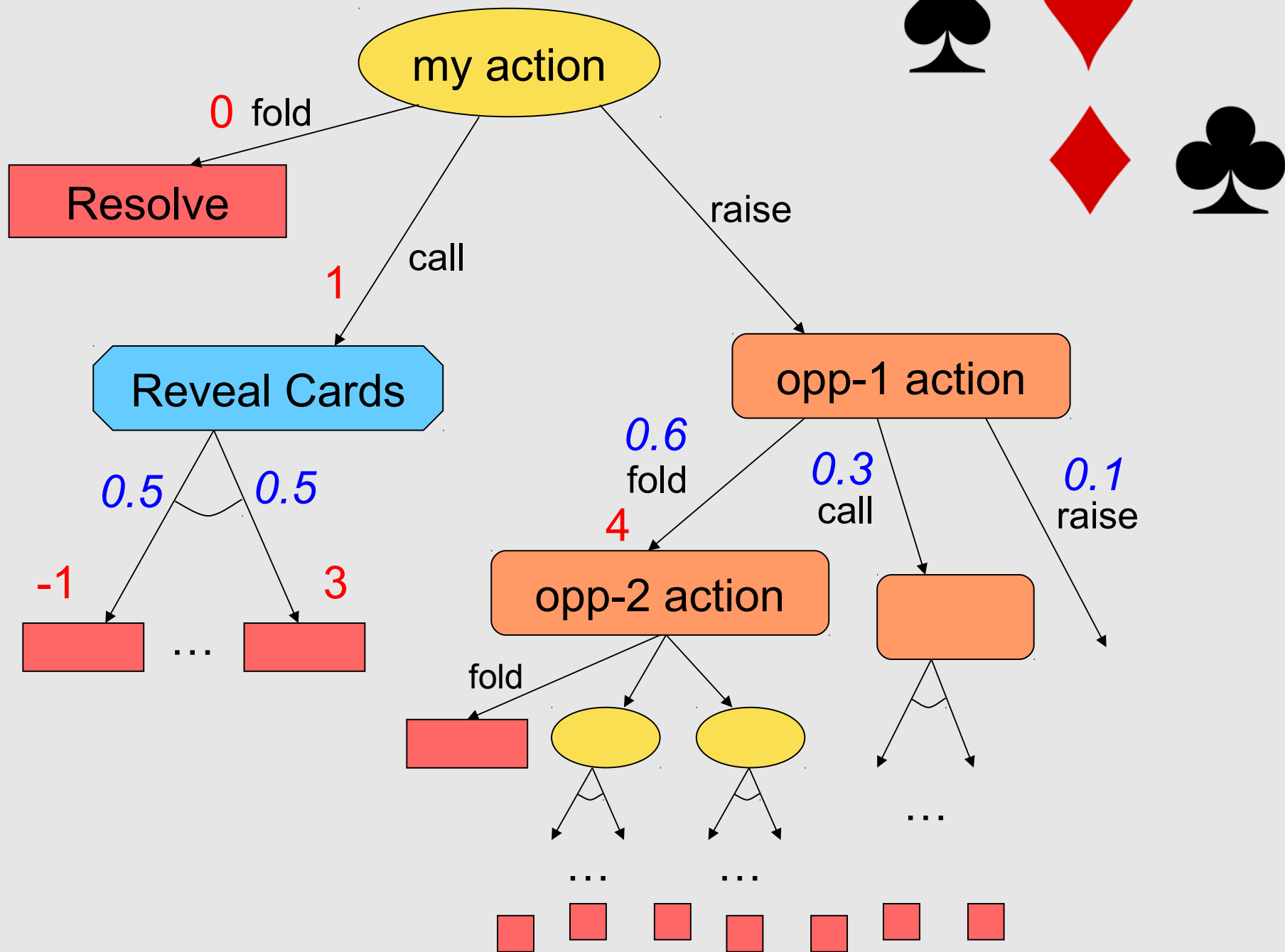


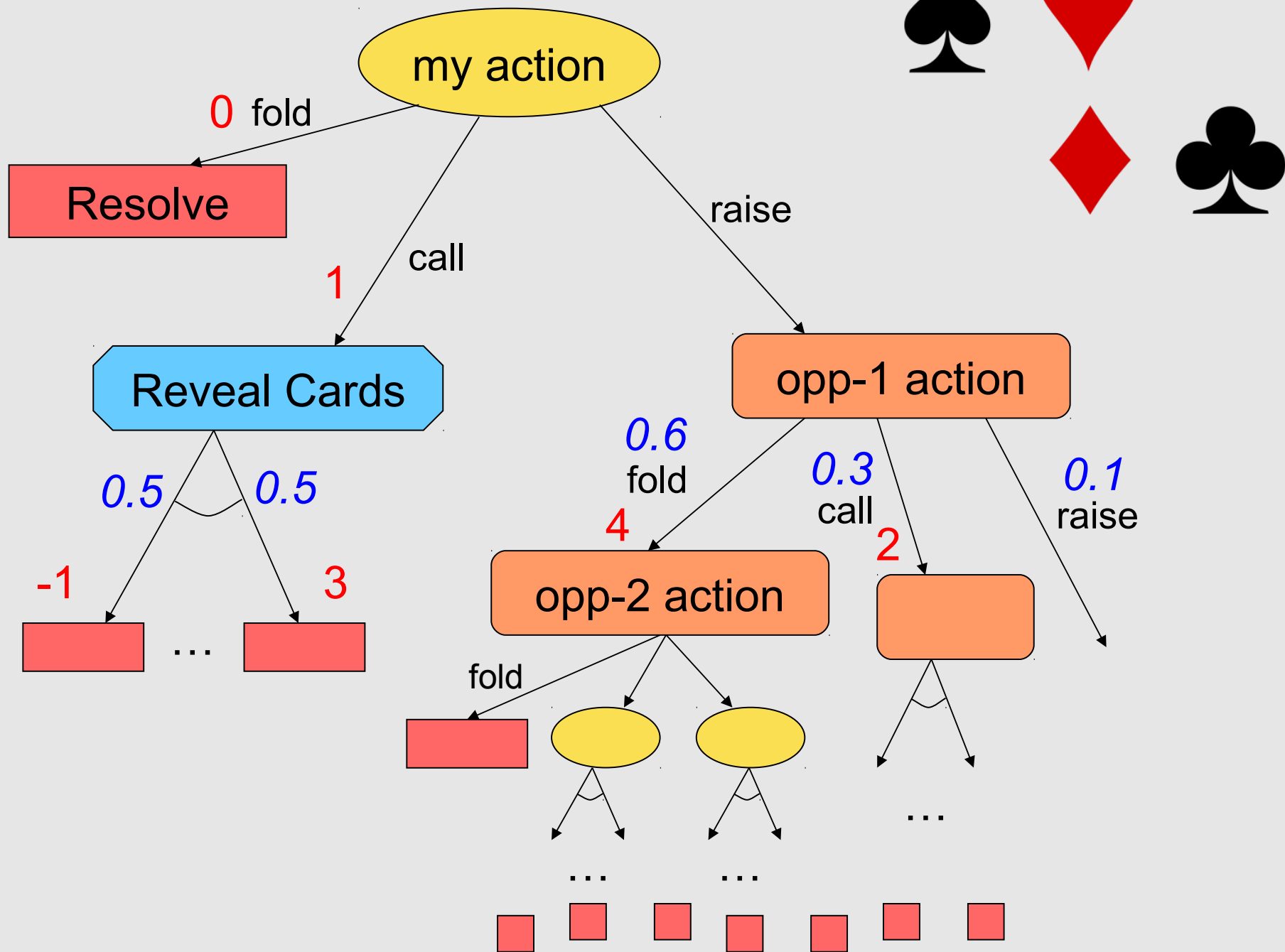




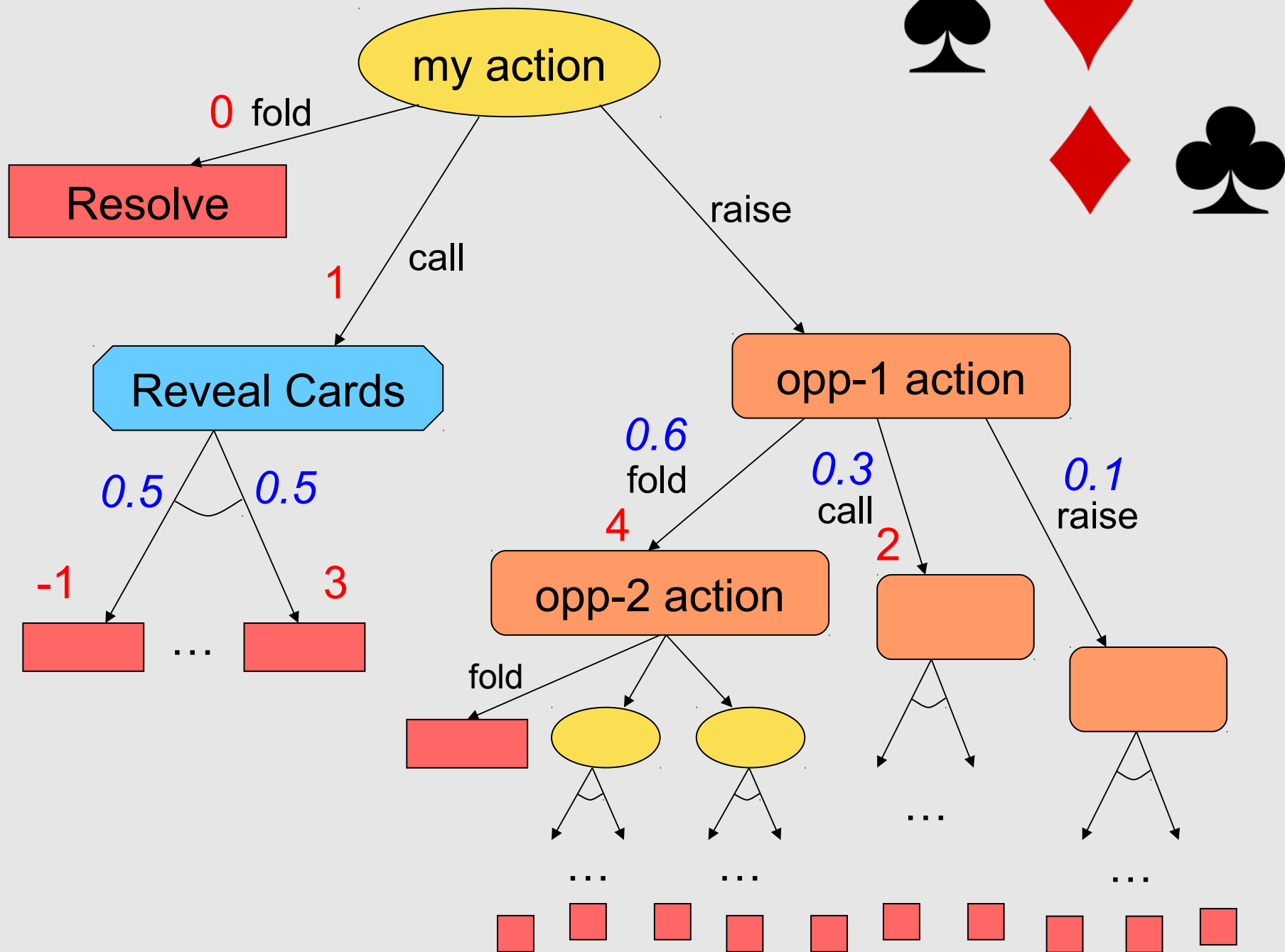


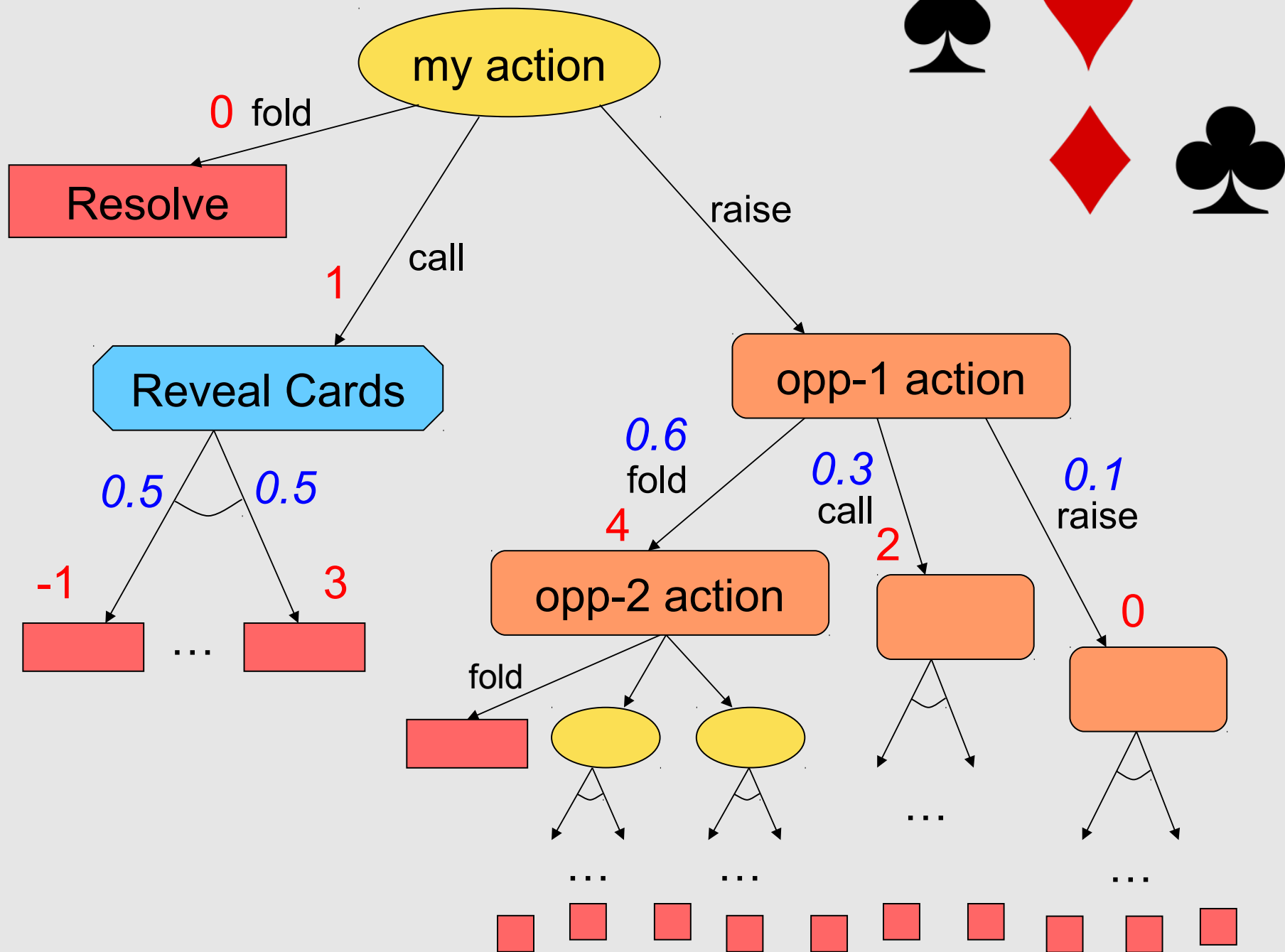


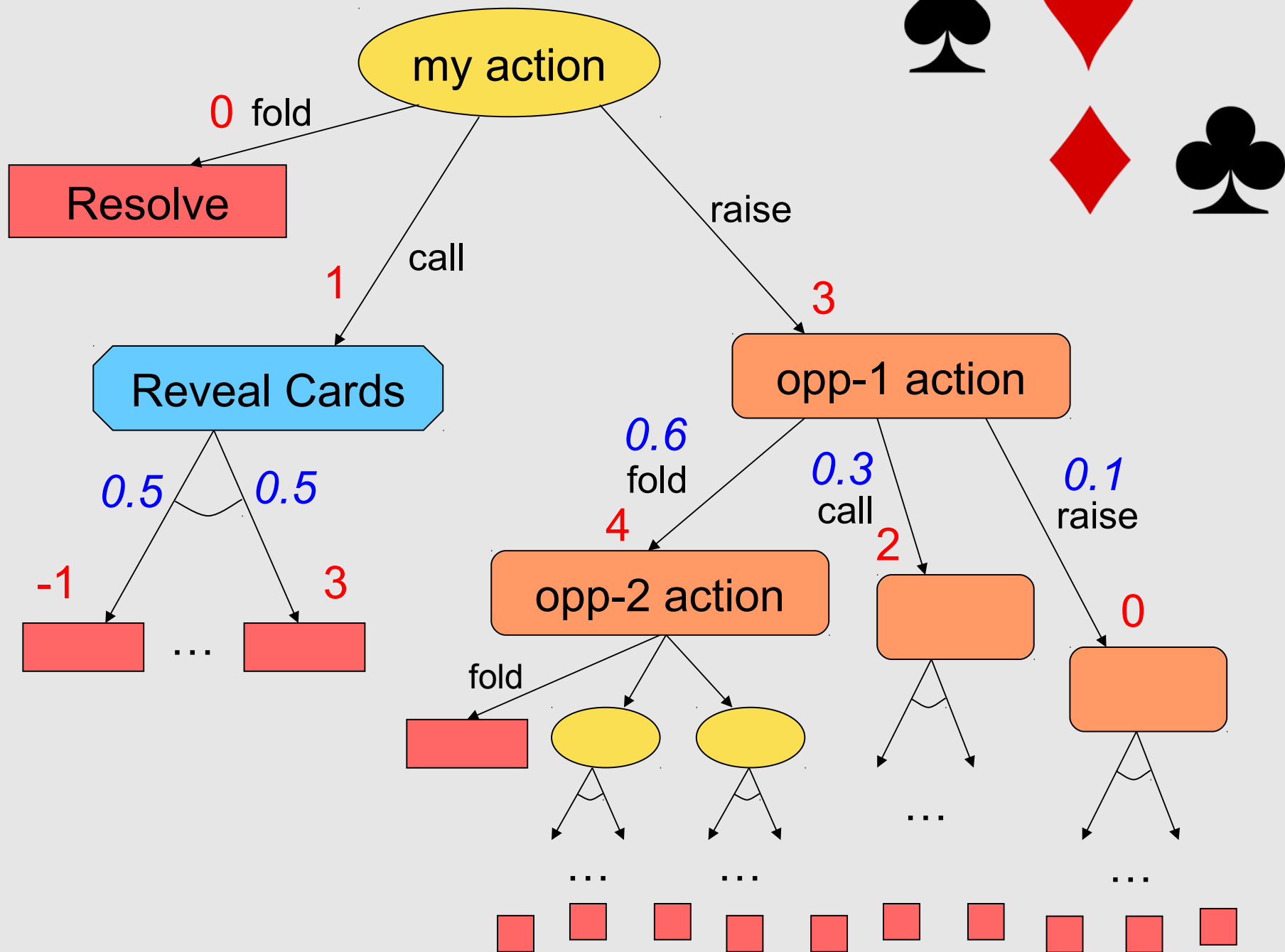




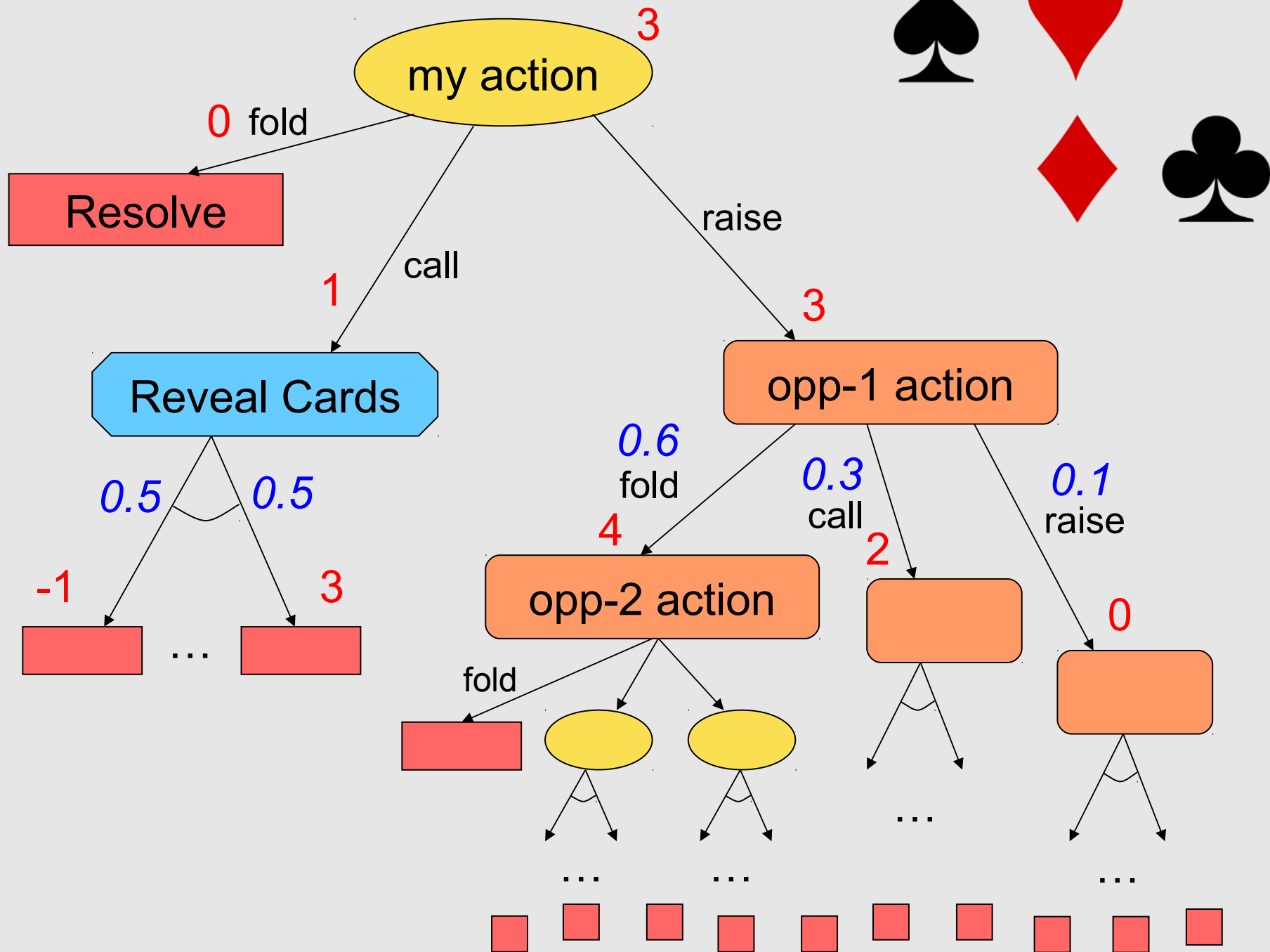










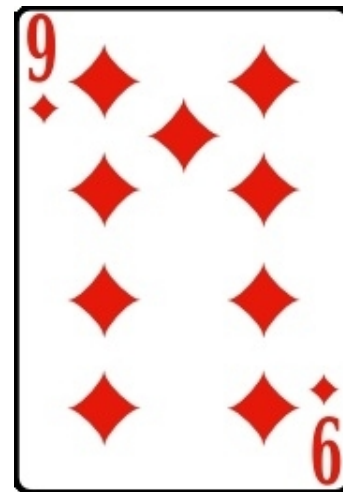
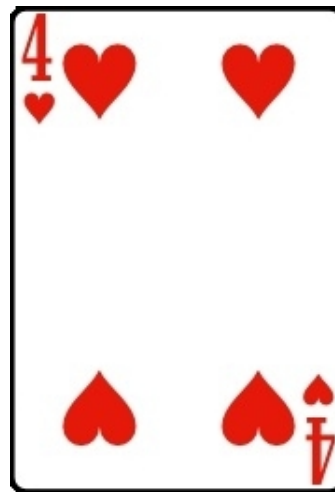
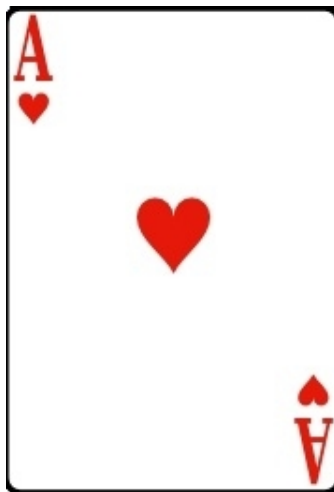
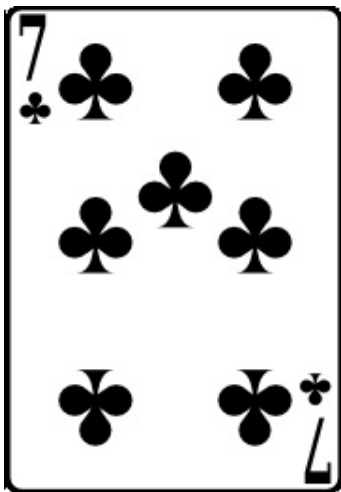


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# Short Experiment





# Opponent Model



- ! Set of probability trees
- ! Weka's M5'
- ! Separate model for

- ! Actions

$$P(A_i | A_0 \dots A_{i-1}, C_0 \dots C_i)$$

- ! Hand cards at showdown

$$P(H | A_0 \dots A_n, C_0 \dots C_n)$$

# Fold Probability

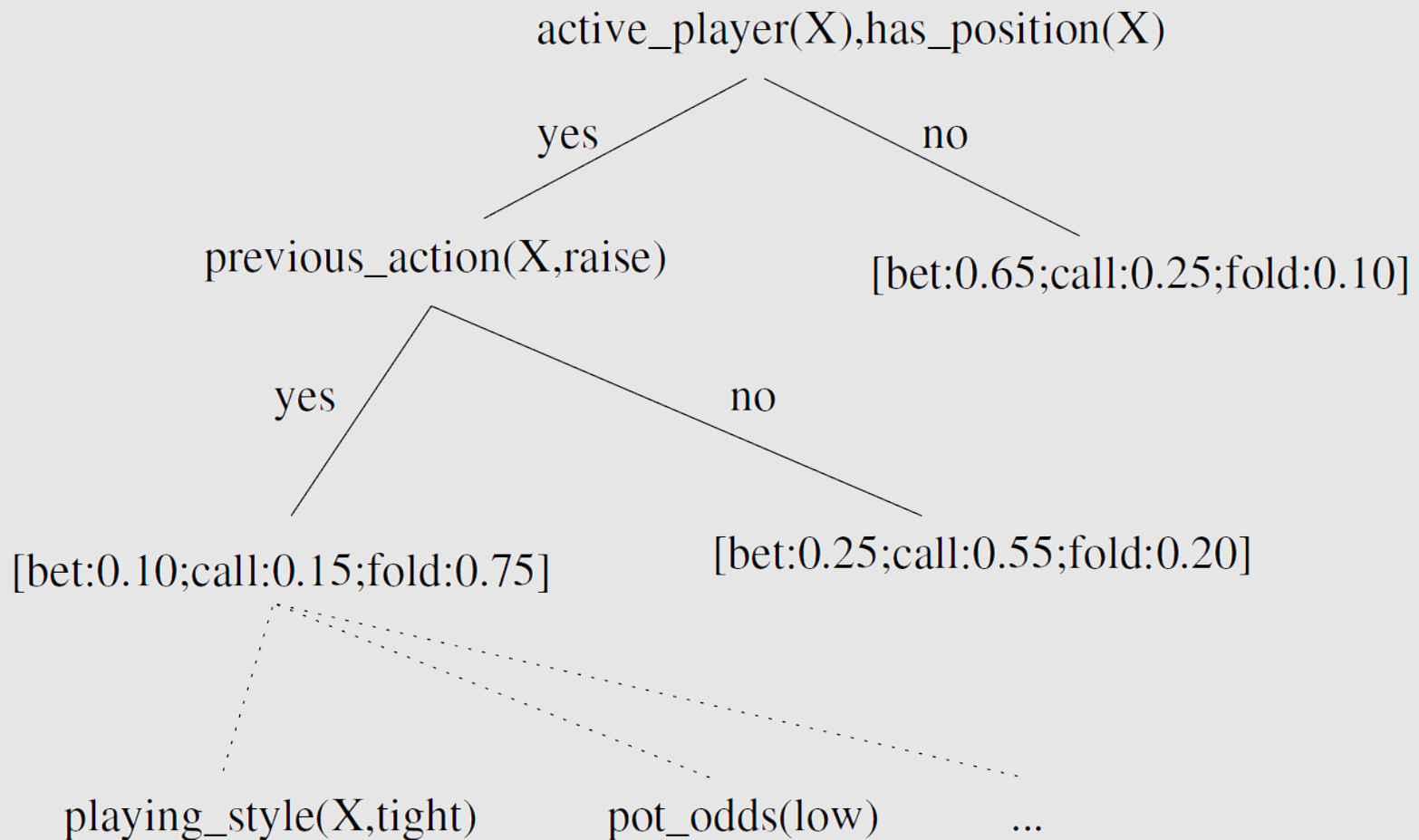


```
nbAllPlayerRaises <= 1.5 :
|   callFrequency <= 0.128 :
|   |   nbActionsThisRound <= 2.5 :
|   |   |   potOdds <= 0.28 :
|   |   |   |   AF <= 2.585 : 0.6904
|   |   |   |   AF > 2.585 :
|   |   |   |   |   potSize <= 3.388 :
|   |   |   |   |   |   round=flop <= 0.5 : 0.8068
|   |   |   |   |   |   round=flop > 0.5 : 0.6896
|   |   |   |   |   potSize > 3.388 : 0.8198
|   |   |   potOdds > 0.28 :
|   |   |   |   stackSize <= 97.238 :
|   |   |   |   |   callFrequency <= 0.038 : 0.8838
|   |   |   |   |   callFrequency > 0.038 :
|   |   |   |   |   |   round=flop <= 0.5 : 0.8316
|   |   |   |   |   |   round=flop > 0.5 :
|   |   |   |   |   |   |   nbSeatedPlayers <= 7.5 : 0.6614
|   |   |   |   |   |   |   nbSeatedPlayers > 7.5 : 0.7793
|   |   |   |   |   stackSize > 97.238 :
|   |   |   |   |   |   potSize <= 4.125 :
|   |   |   |   |   |   |   foldFrequency <= 0.813 : 0.7839
|   |   |   |   |   |   |   foldFrequency > 0.813 : 0.9037
|   |   |   |   |   |   potSize > 4.125 : 0.8623
|   |   |   nbActionsThisRound > 2.5 :
|   |   |   |   potOdds <= 0.218 :
|   |   |   |   |   callFrequency <= 0.067 : 0.8753
|   |   |   |   |   callFrequency > 0.067 : 0.7661
|   |   |   |   potOdds > 0.218 :
|   |   |   |   |   AF <= 2.654 : 0.8818
|   |   |   |   |   AF > 2.654 : 0.921
```



# (Can also be relational)

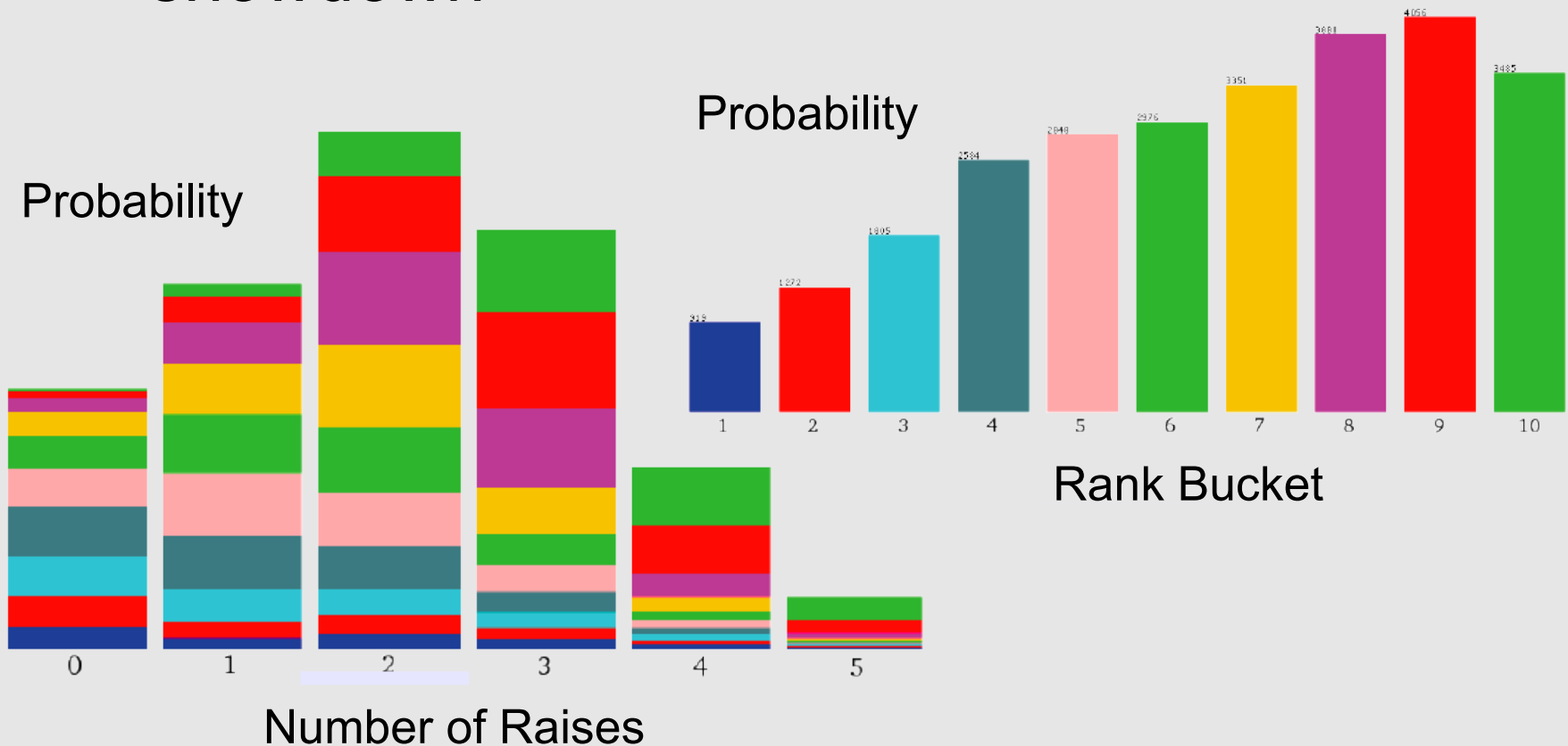
! Tilde probability tree [Ponsen08]





# Opponent Ranks

- ! Learn distribution of hand ranks at showdown





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# Traversing the tree



- ! Limit Texas Hold'em

- !  $10^{18}$  nodes

- ! Fully traversable

- ! No-limit

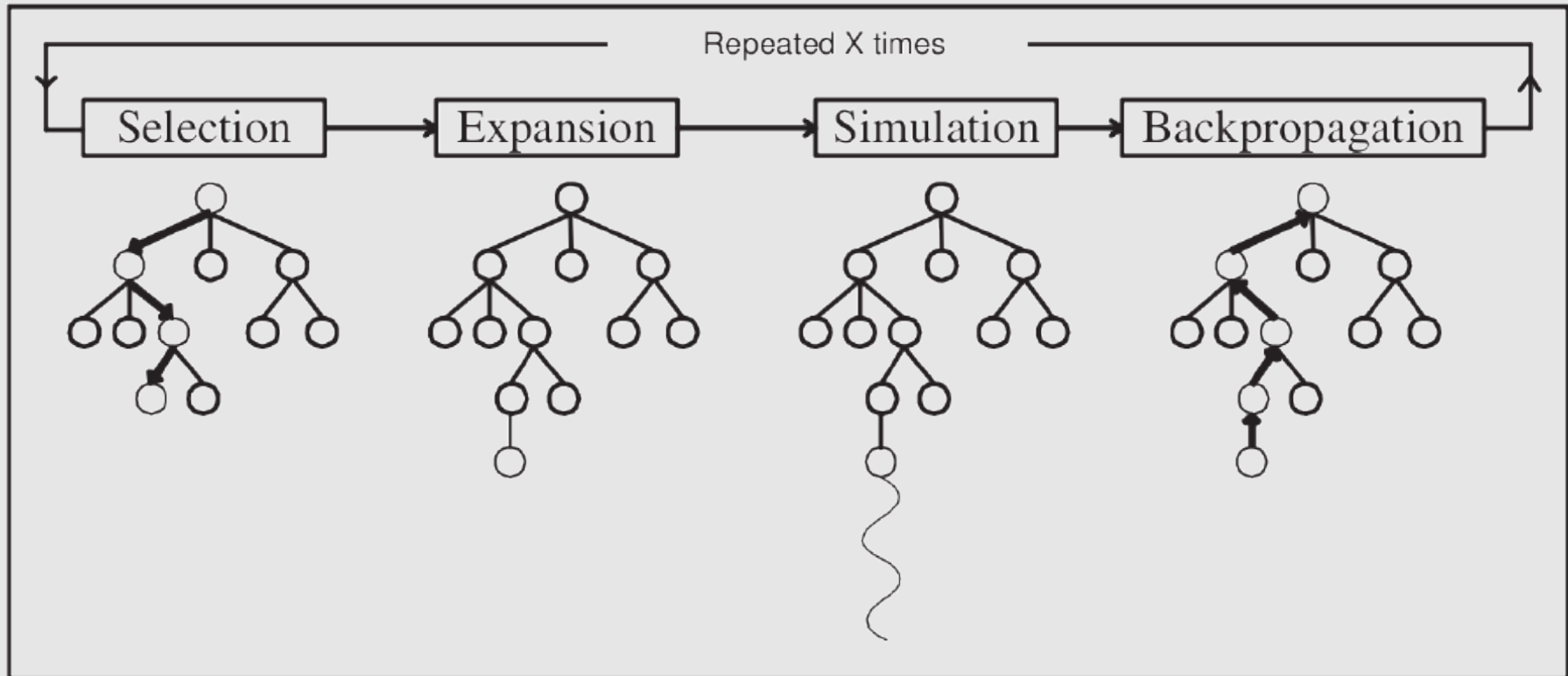
- !  $>10^{71}$  nodes

- ! Too large to traverse

- ! Sampled, not searched

- ! Monte-Carlo Tree Search

# Monte-Carlo Tree Search



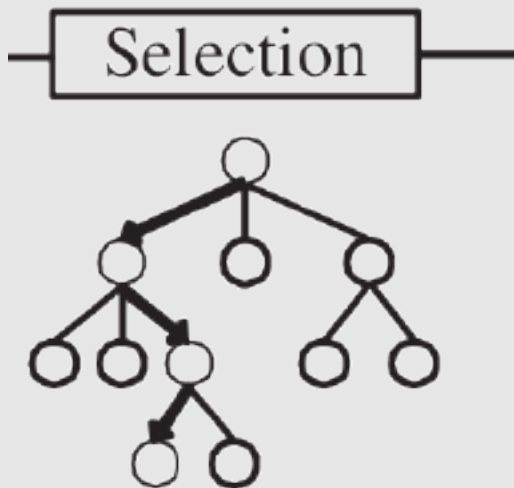
[Chaslot08]

# Selection



In each node:

$\hat{V}(P)$  is an estimate of the reward  $r(P)$   
 $T(P)$  is the number of samples





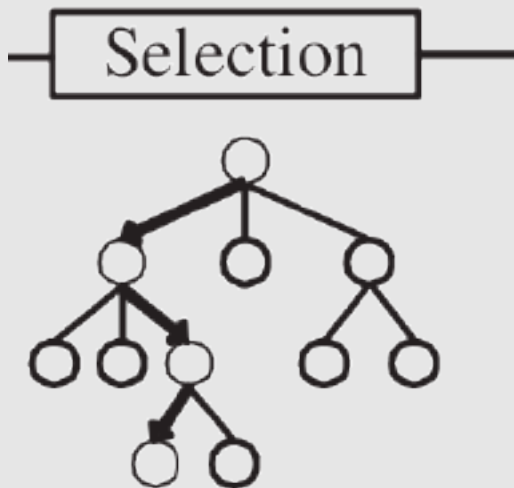
# Selection



In each node:

$\hat{V}(P)$  is an estimate of the reward  $r(P)$   
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! UCT (Multi-Armed Bandit)



$$\hat{V}(c_i) + C \sqrt{\frac{\ln T(P)}{T(c_i)}}$$

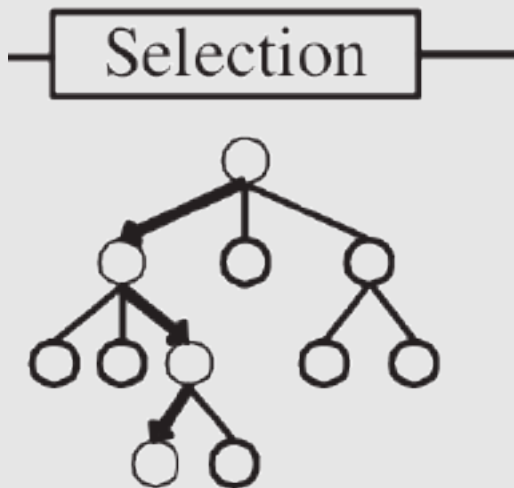
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## ! UCT (Multi-Armed Bandit)



$$\hat{V}(c_i) + C \sqrt{\frac{\ln T(P)}{T(c_i)}}$$

exploitation

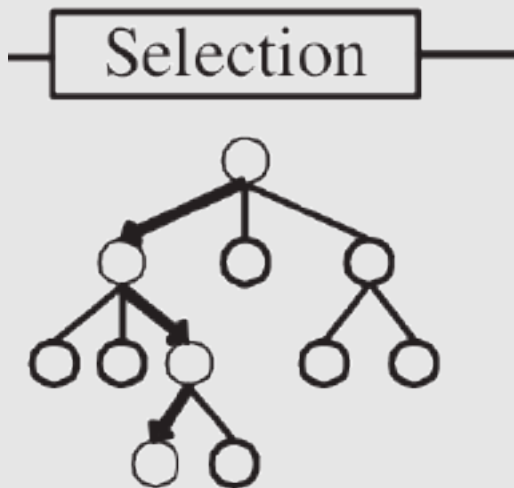
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exploitation

exploration

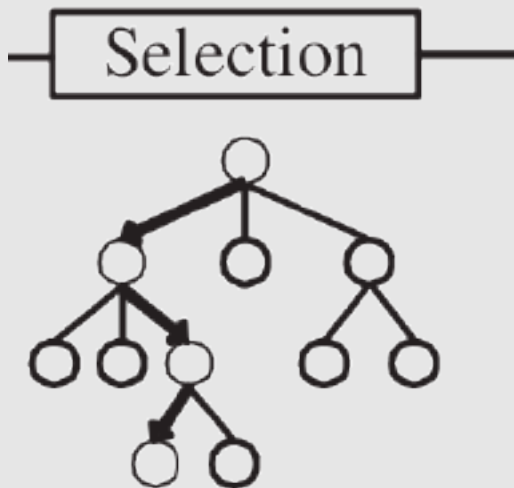
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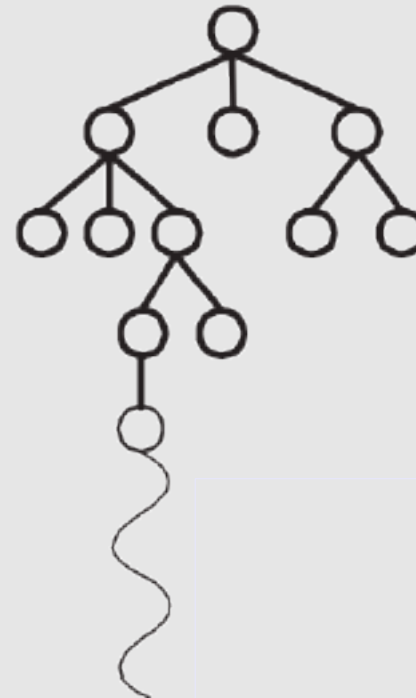
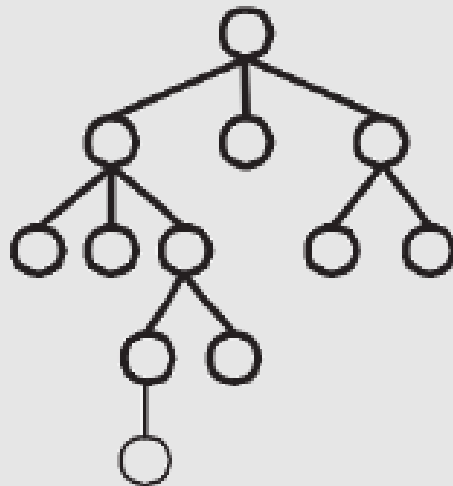
exploitation

exploration

## ! CrazyStone

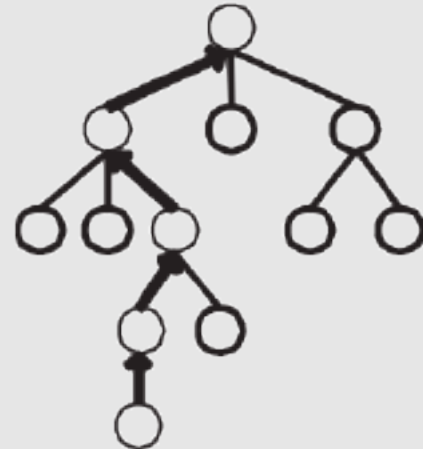
$$P(c_i) \sim \exp \left( -2.4 \frac{\hat{V}(c_{best}) - \hat{V}(c_i)}{\sqrt{2(\bar{\sigma}(c_{best})^2 + \bar{\sigma}(c_i)^2)}} \right)$$

# Expansion Simulation



A collection of five playing card suits arranged in two rows. The top row contains a black Spade and a red Heart. The bottom row contains a red Diamond and a black Club.

→ Backpropagation ←





# Backpropagation

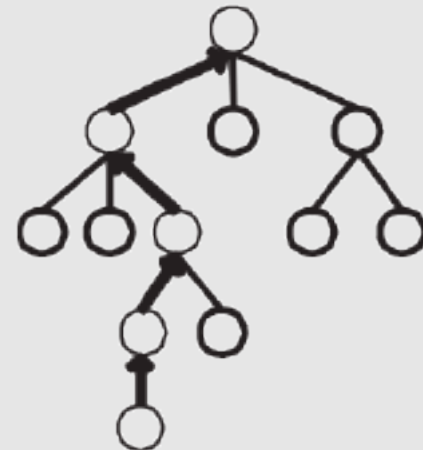


$\hat{V}(P)$  is an estimate of the reward  $r(P)$   
 $T(P)$  is the number of samples

## ! Sample-weighted average

$$\hat{V}(n) = \sum_j \frac{T(c_j)}{T(n)} \hat{V}(c_j)$$

→ Backpropagation ←



A collection of five playing card suits arranged in two rows. The top row contains a black Spade and a red Heart. The bottom row contains a red Diamond and a black Club.

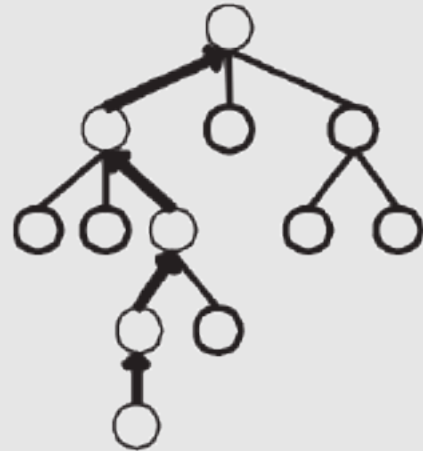
$\hat{V}(P)$  is an estimate of the reward  $r(P)$   
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- Sample-weighted average

$$\hat{V}(n) = \sum_j \frac{T(c_j)}{T(n)} \hat{V}(c_j)$$

## ! Maximum child

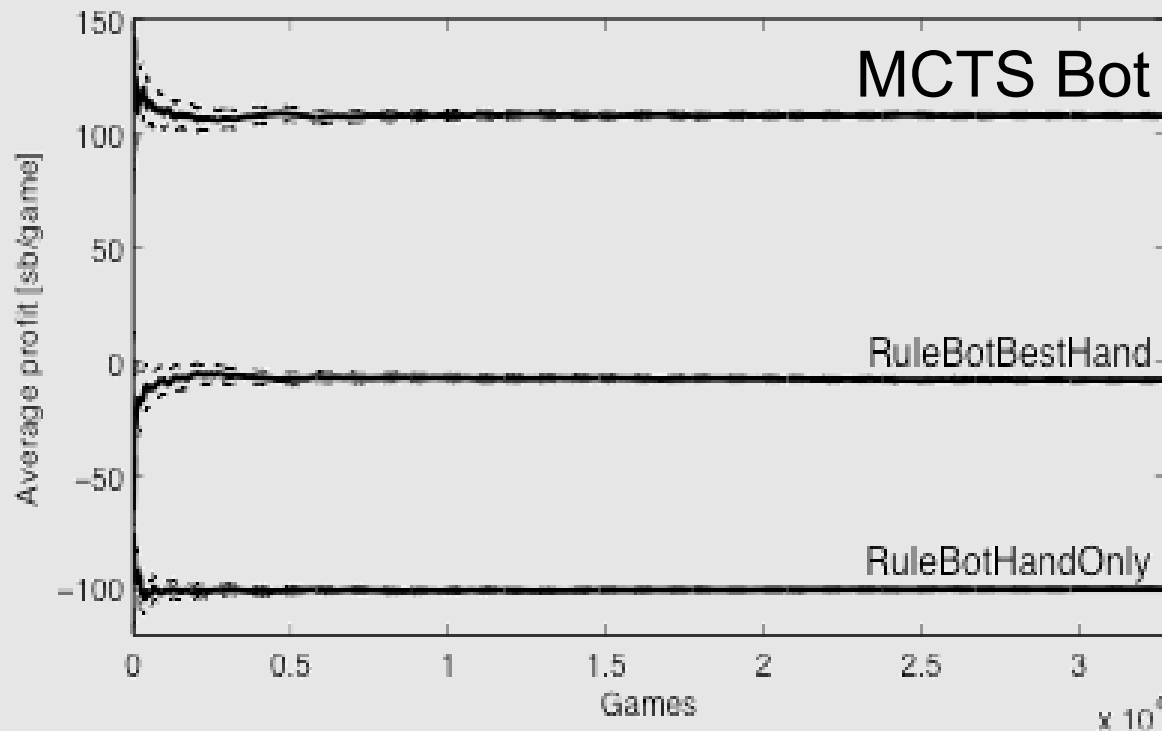
$$\hat{V}(P) = \max_j \hat{V}(c_j)$$



# Initial experiments



- ! 1\*MCTS + 2\*rule based
- ! Exploitative!



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# MCTS for games with uncertainty?



- ! Expected reward distributions (ERD)
- ! Sample selection using ERD
- ! Backpropagation of ERD

# Expected reward distribution



MiniMax

Estimating

$$r(P)$$

10 samples

100 samples

$\infty$  samples

Variance

# Expected reward distribution

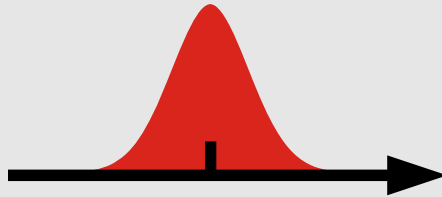


MiniMax

Estimating

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Variance

# Expected reward distribution

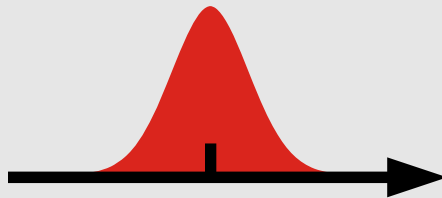


MiniMax

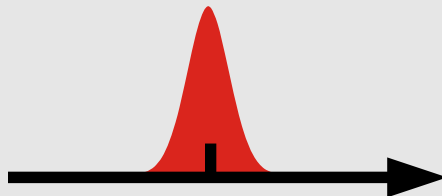
Estimating

$r(P)$

10 samples



100 samples



$\infty$  samples

Variance

# Expected reward distribution

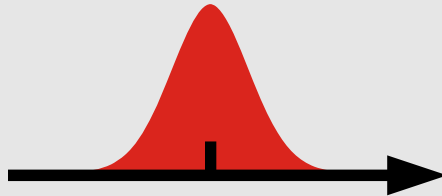


MiniMax

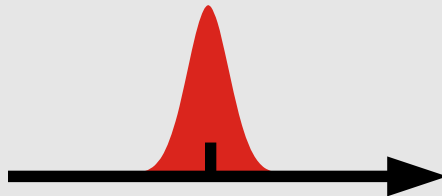
Estimating

$r(P)$

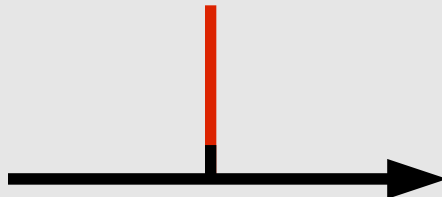
10 samples



100 samples



$\infty$  samples



Variance

# Expected reward distribution

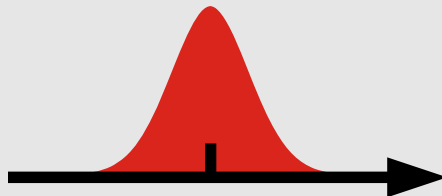


MiniMax

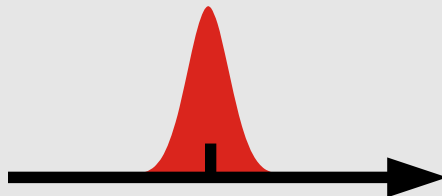
Estimating

$r(P)$

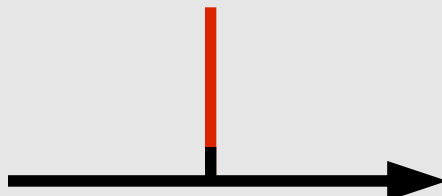
10 samples



100 samples



$\infty$  samples



Variance

*Sampling*



# Expected reward distribution



MiniMax

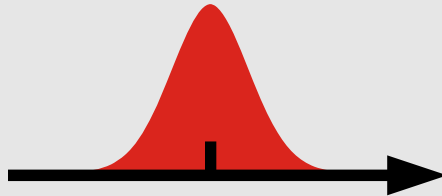
ExpectiMax/MixiMax

Estimating

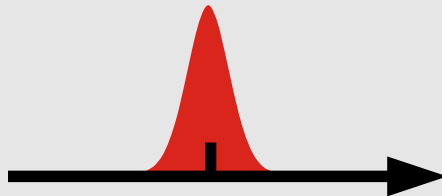
$r(P)$

$r(P)$

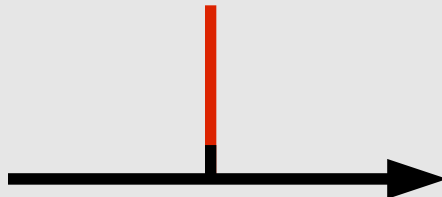
10 samples



100 samples



$\infty$  samples



Variance

*Sampling*

# Expected reward distribution



MiniMax

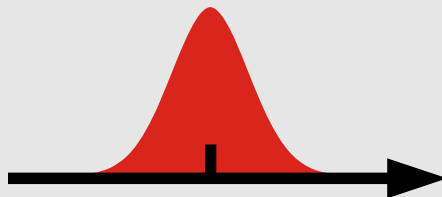
ExpectiMax/MixiMax

Estimating

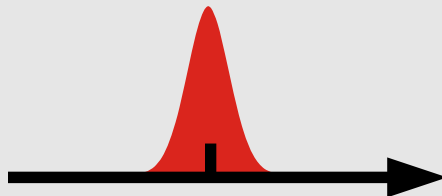
$r(P)$

$r(P)$

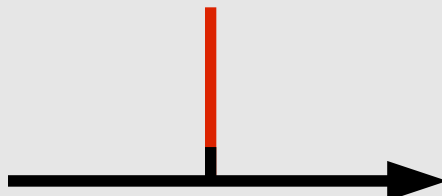
10 samples



100 samples



$\infty$  samples



Variance

*Sampling*

# Expected reward distribution



MiniMax

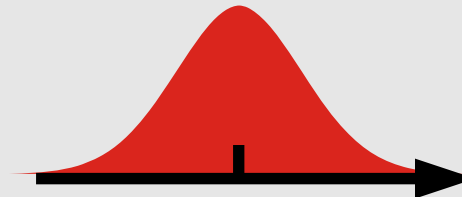
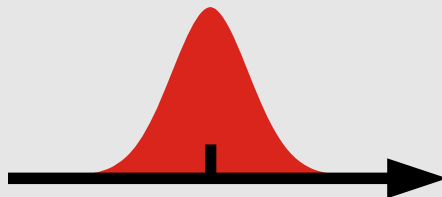
ExpectiMax/MixiMax

Estimating

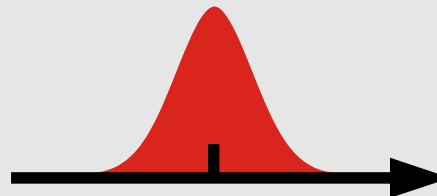
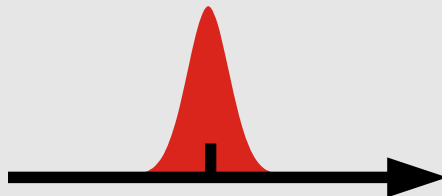
$r(P)$

$r(P)$

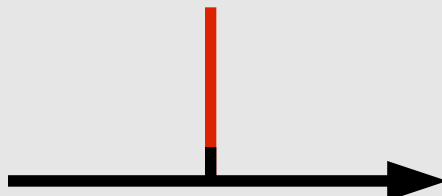
10 samples



100 samples



$\infty$  samples



Variance

*Sampling*

# Expected reward distribution



MiniMax

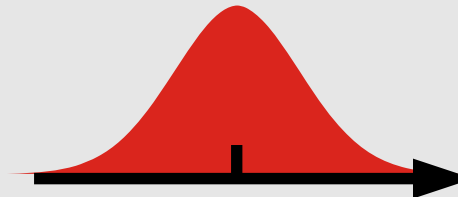
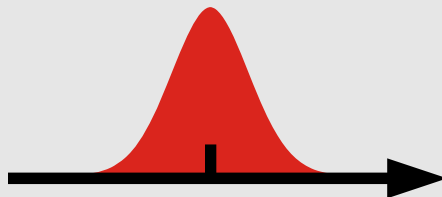
ExpectiMax/MixiMax

Estimating

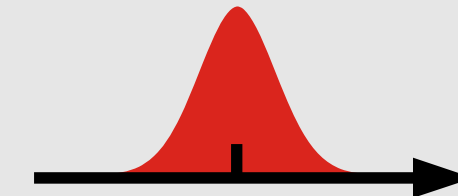
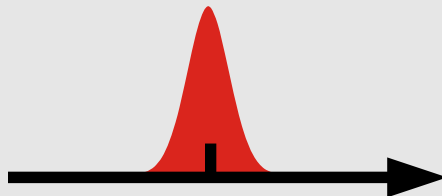
$r(P)$

$r(P)$

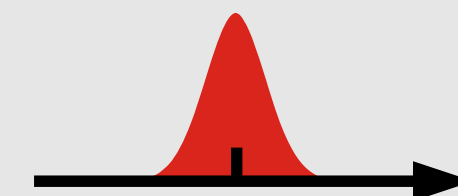
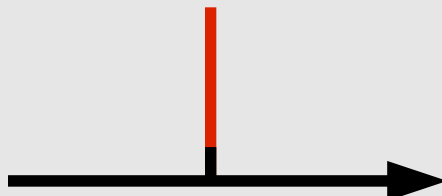
10 samples



100 samples



$\infty$  samples



Variance

*Sampling*

# Expected reward distribution



MiniMax

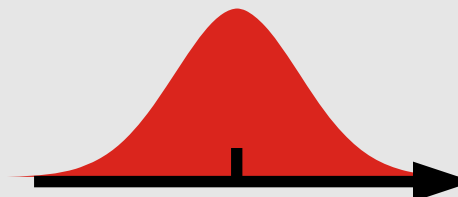
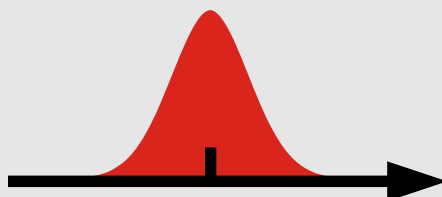
ExpectiMax/MixiMax

Estimating

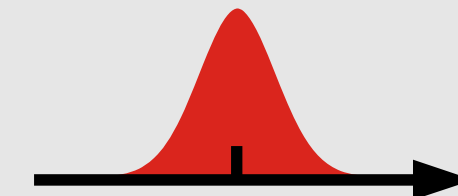
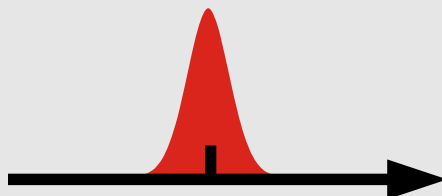
$r(P)$

$r(P)$

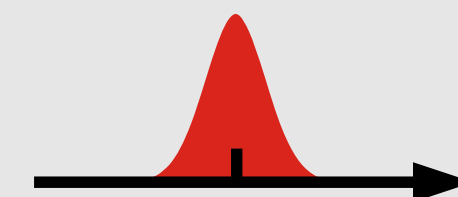
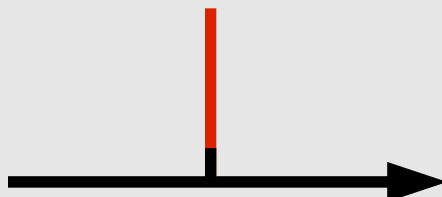
10 samples



100 samples



$\infty$  samples



Variance

*Sampling*

*Uncertainty + Sampling*

# Expected reward distribution



MiniMax

ExpectiMax/MixiMax

ExpectiMax/MixiMax

Estimating

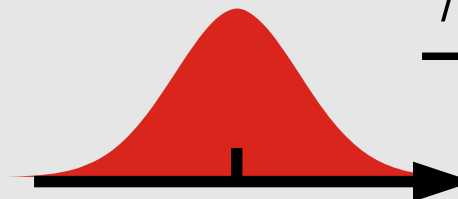
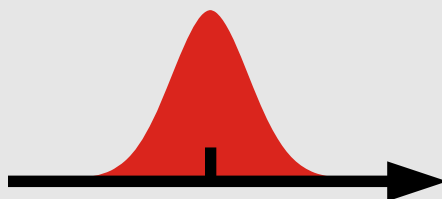
$r(P)$

$r(P)$

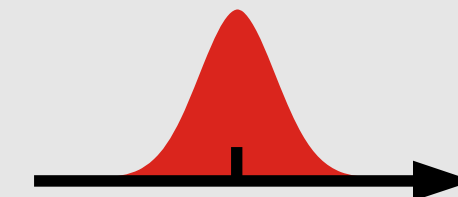
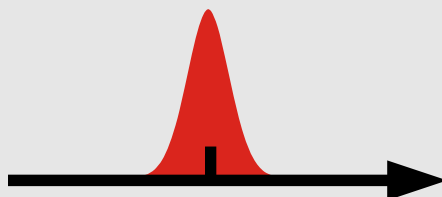
$\mathbb{E}[r(P)]$

$/ T(P)$

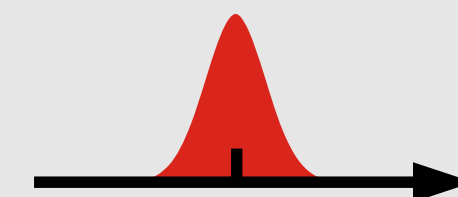
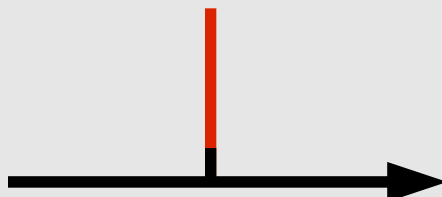
10 samples



100 samples



$\infty$  samples



Variance

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*Uncertainty + Sampling*

# Expected reward distribution



MiniMax

ExpectiMax/MixiMax

ExpectiMax/MixiMax

Estimating

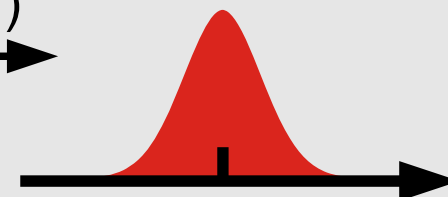
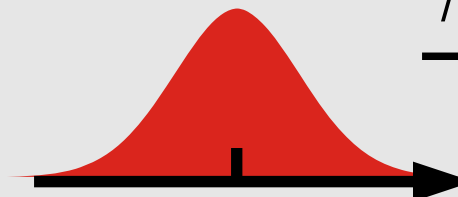
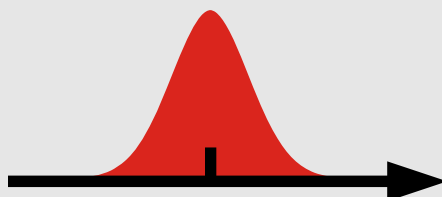
$r(P)$

$r(P)$

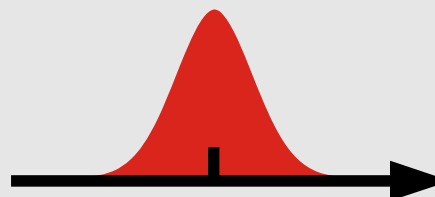
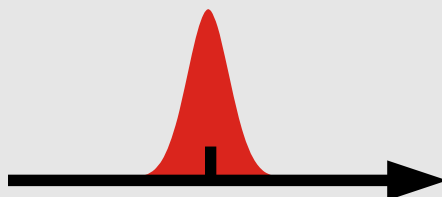
$\mathbb{E}[r(P)]$

$/ T(P)$

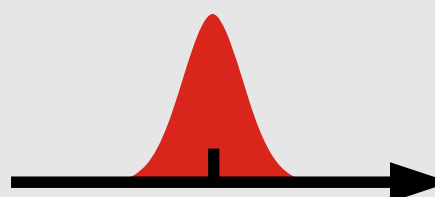
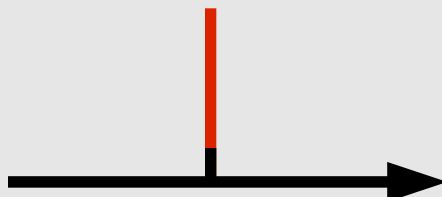
10 samples



100 samples



$\infty$  samples



Variance

*Sampling*

*Uncertainty + Sampling*



# Expected reward distribution



MiniMax

ExpectiMax/MixiMax

ExpectiMax/MixiMax

Estimating

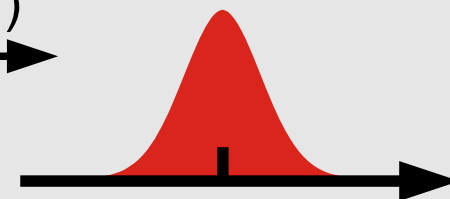
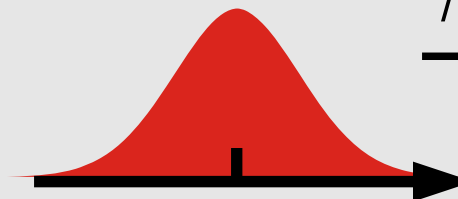
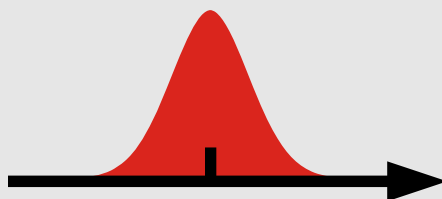
$r(P)$

$r(P)$

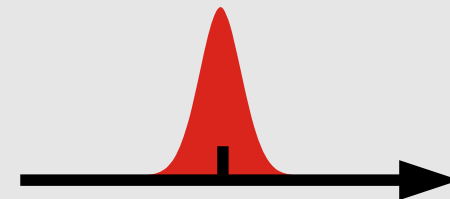
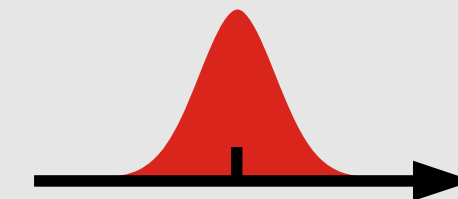
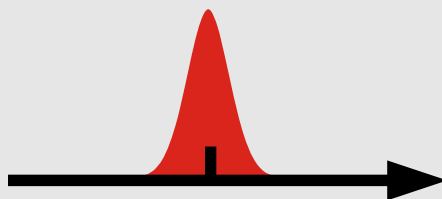
$\mathbb{E}[r(P)]$

$/ T(P)$

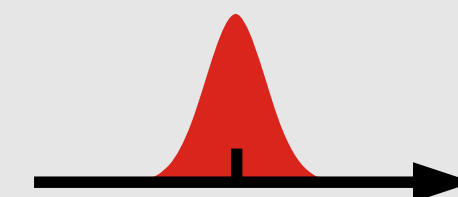
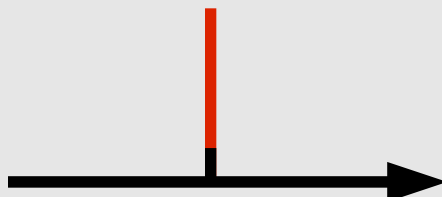
10 samples



100 samples



$\infty$  samples



Variance

*Sampling*

*Uncertainty + Sampling*

# Expected reward distribution



MiniMax

ExpectiMax/MixiMax

ExpectiMax/MixiMax

Estimating

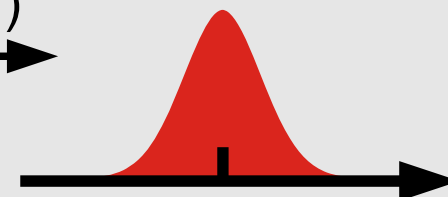
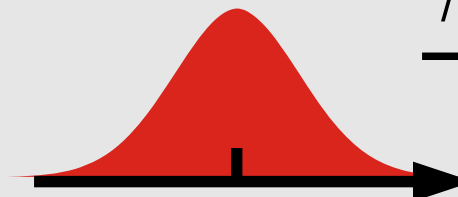
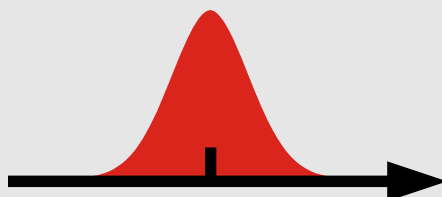
$r(P)$

$r(P)$

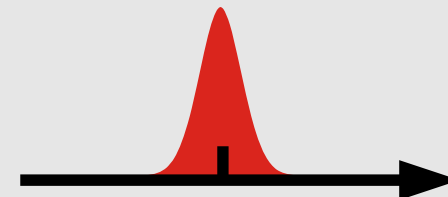
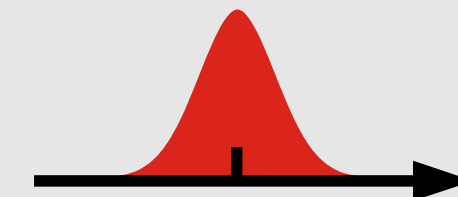
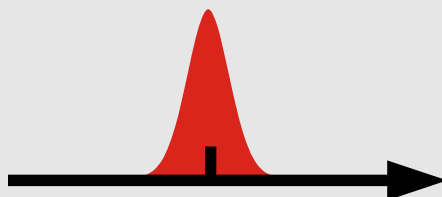
$\mathbb{E}[r(P)]$

$/ T(P)$

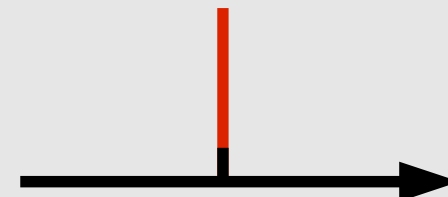
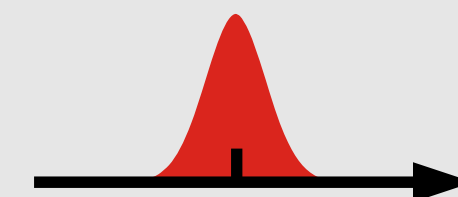
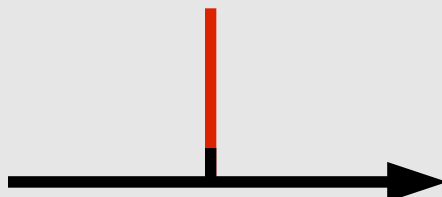
10 samples



100 samples



$\infty$  samples



Variance

*Sampling*

*Uncertainty + Sampling*

# Expected reward distribution



MiniMax

ExpectiMax/MixiMax

ExpectiMax/MixiMax

Estimating

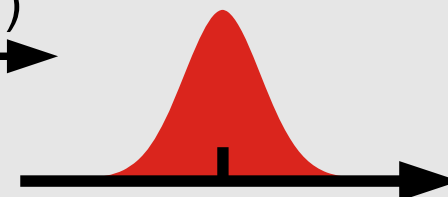
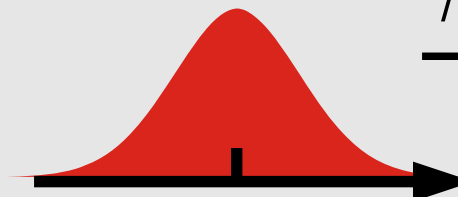
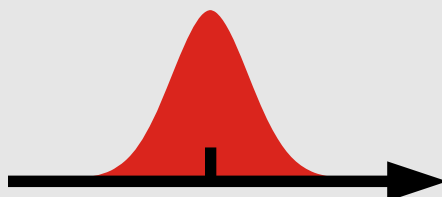
$r(P)$

$r(P)$

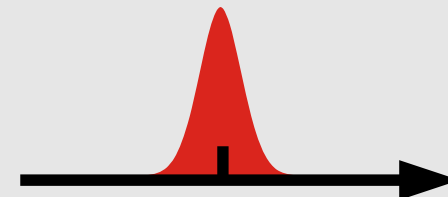
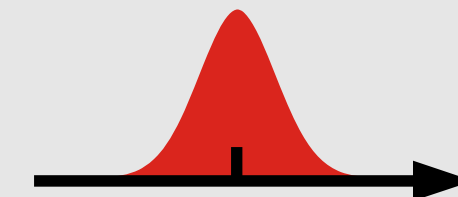
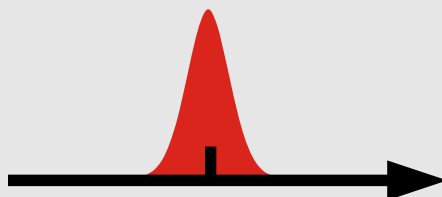
$\mathbb{E}[r(P)]$

$/ T(P)$

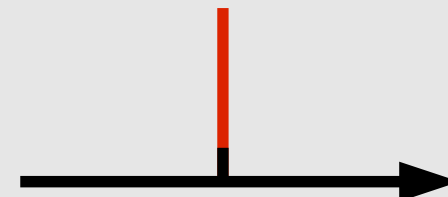
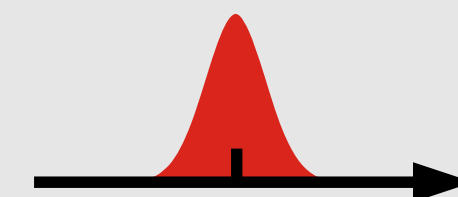
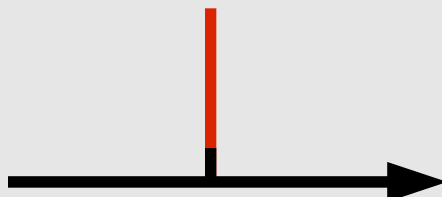
10 samples



100 samples



$\infty$  samples



Variance

*Sampling*

*Uncertainty + Sampling*

*Sampling*

# Expected reward distribution



MiniMax

ExpectiMax/MixiMax

ExpectiMax/MixiMax

Estimating

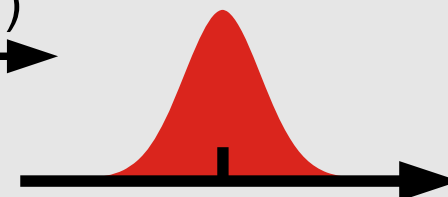
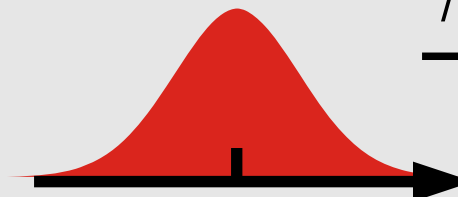
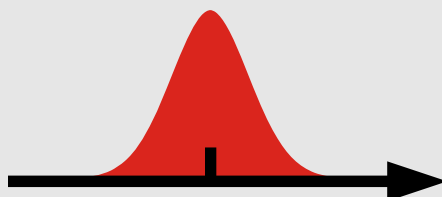
$r(P)$

$r(P)$

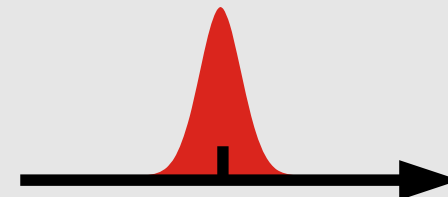
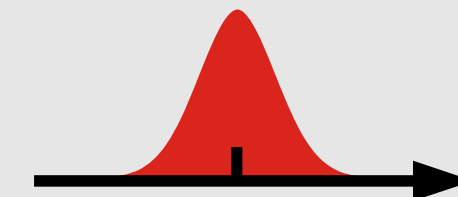
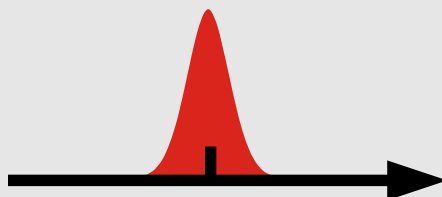
$\mathbb{E}[r(P)]$

/  $T(P)$

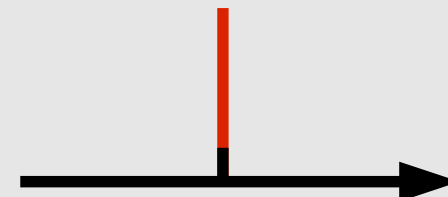
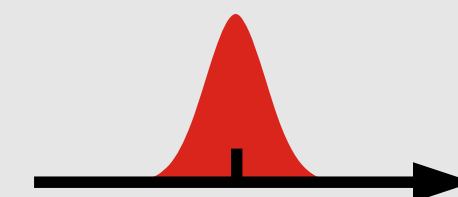
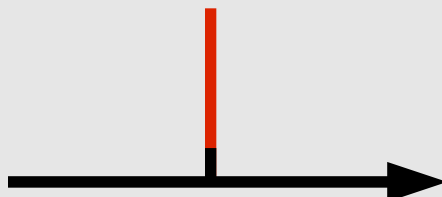
10 samples



100 samples



$\infty$  samples



Variance

*Sampling*

*Uncertainty + Sampling*

*Sampling*



# ERD selection strategy



- ! Objective?
  - ! Find maximum expected reward
  - ! Sample more in subtrees with
    - (1) High expected reward
    - (2) Uncertain estimate
- ! UCT does (1) but not really (2)
- ! CrazyStone does (1) and (2) for deterministic games (Go)
- ! **UCT+ selection:**  $\hat{V}(c_i) + C \cdot \sigma_{\hat{V}, c_i}$ 
  - (1)
  - (2)

# ERD selection strategy



- ! Objective?
  - ! Find maximum expected reward
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- ! **UCT+ selection:**  $\hat{V}(c_i) + C \cdot \sigma_{\hat{V}, c_i}$

*“Expected value under perfect play”*

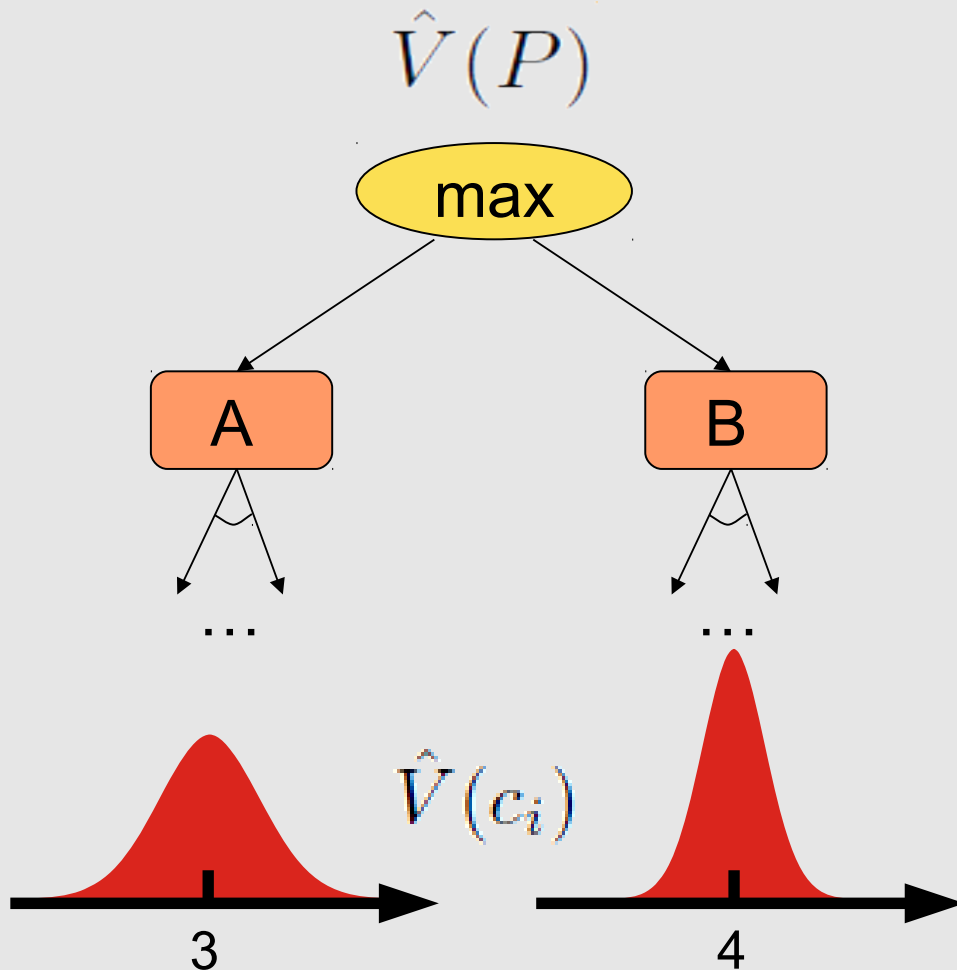
# ERD selection strategy



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*“Measure of uncertainty due to sampling”*

# ERD max-distribution backpropagation

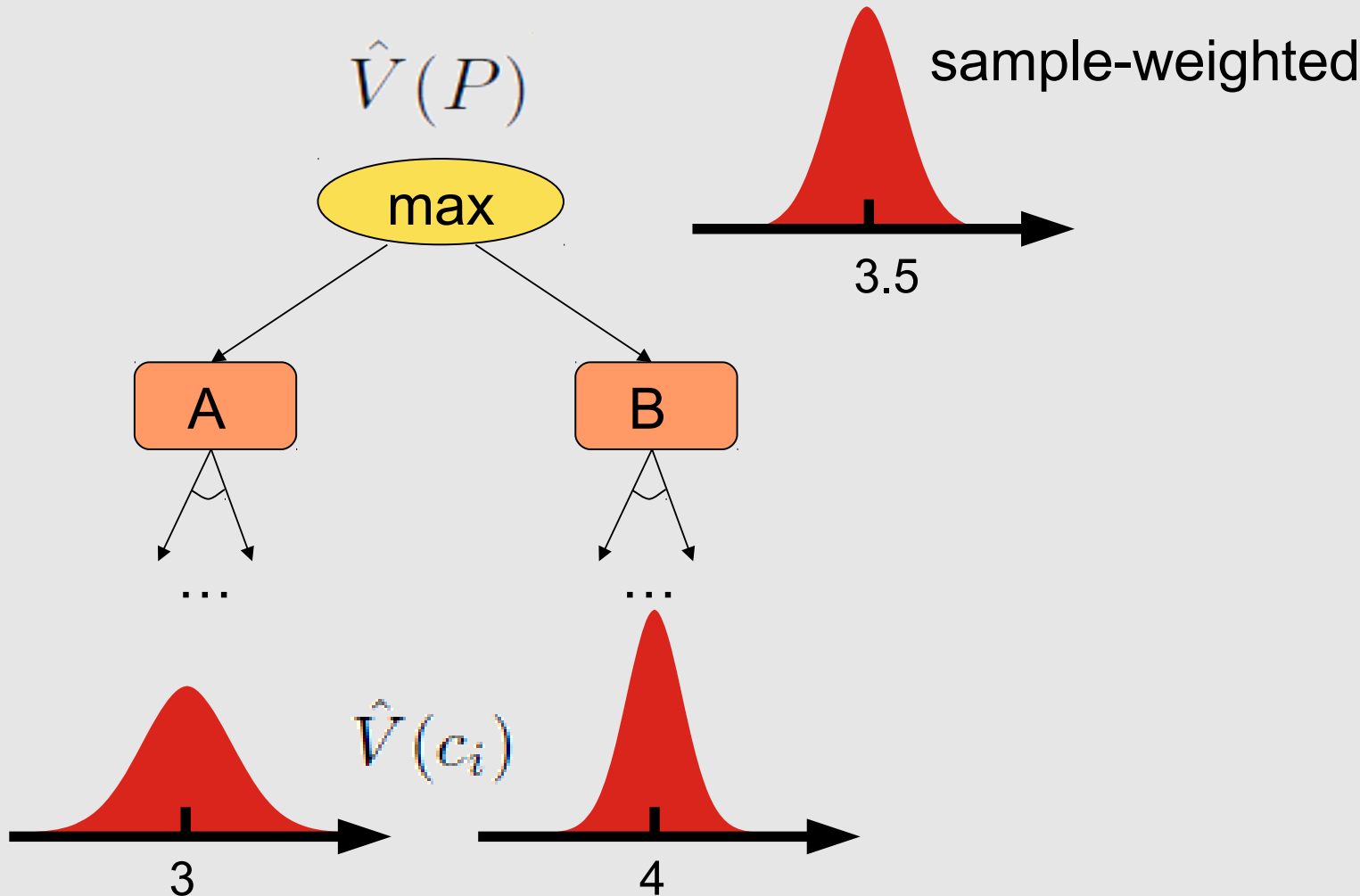




# ERD max-distribution



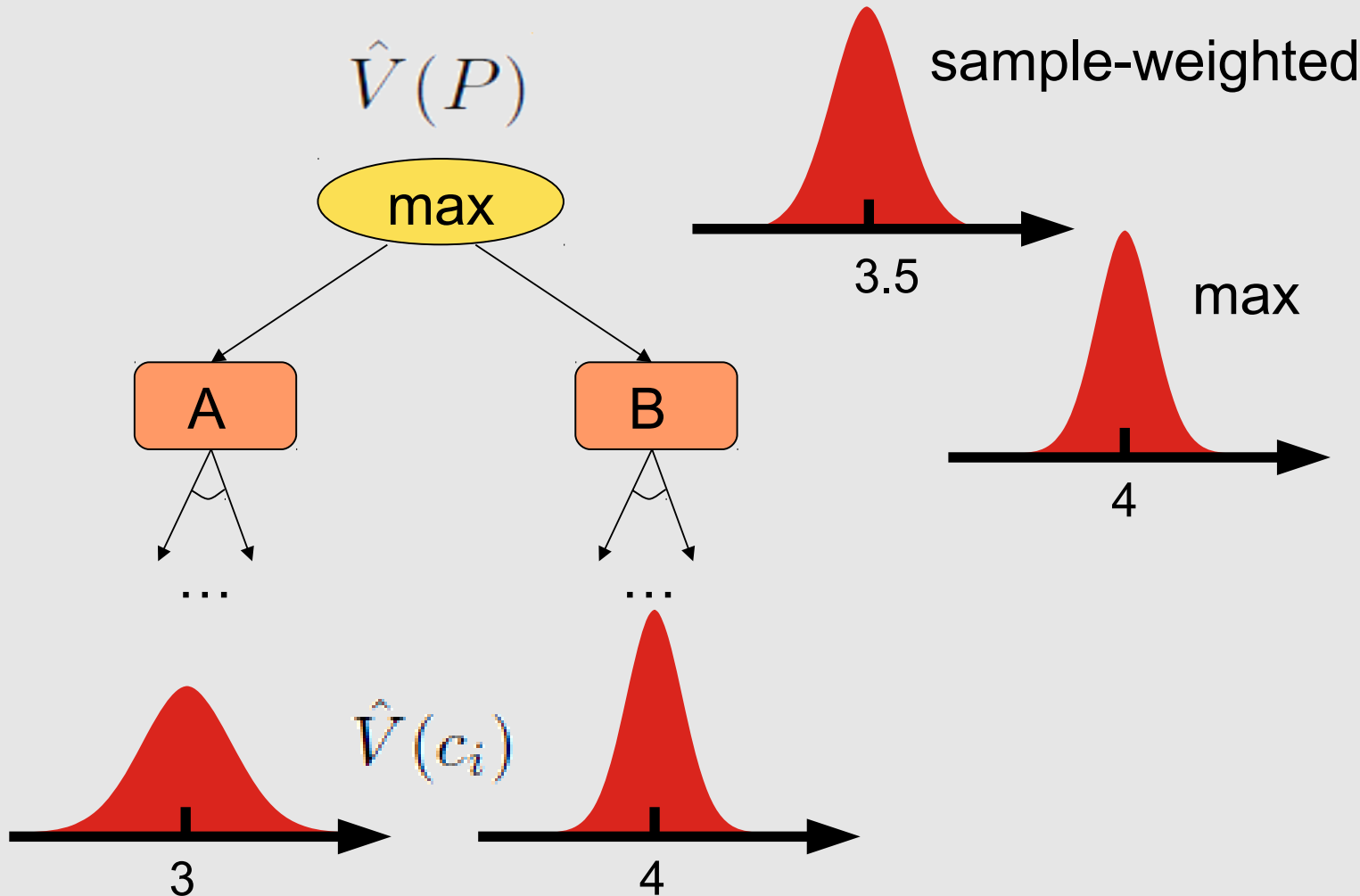
## backpropagation



# ERD max-distribution

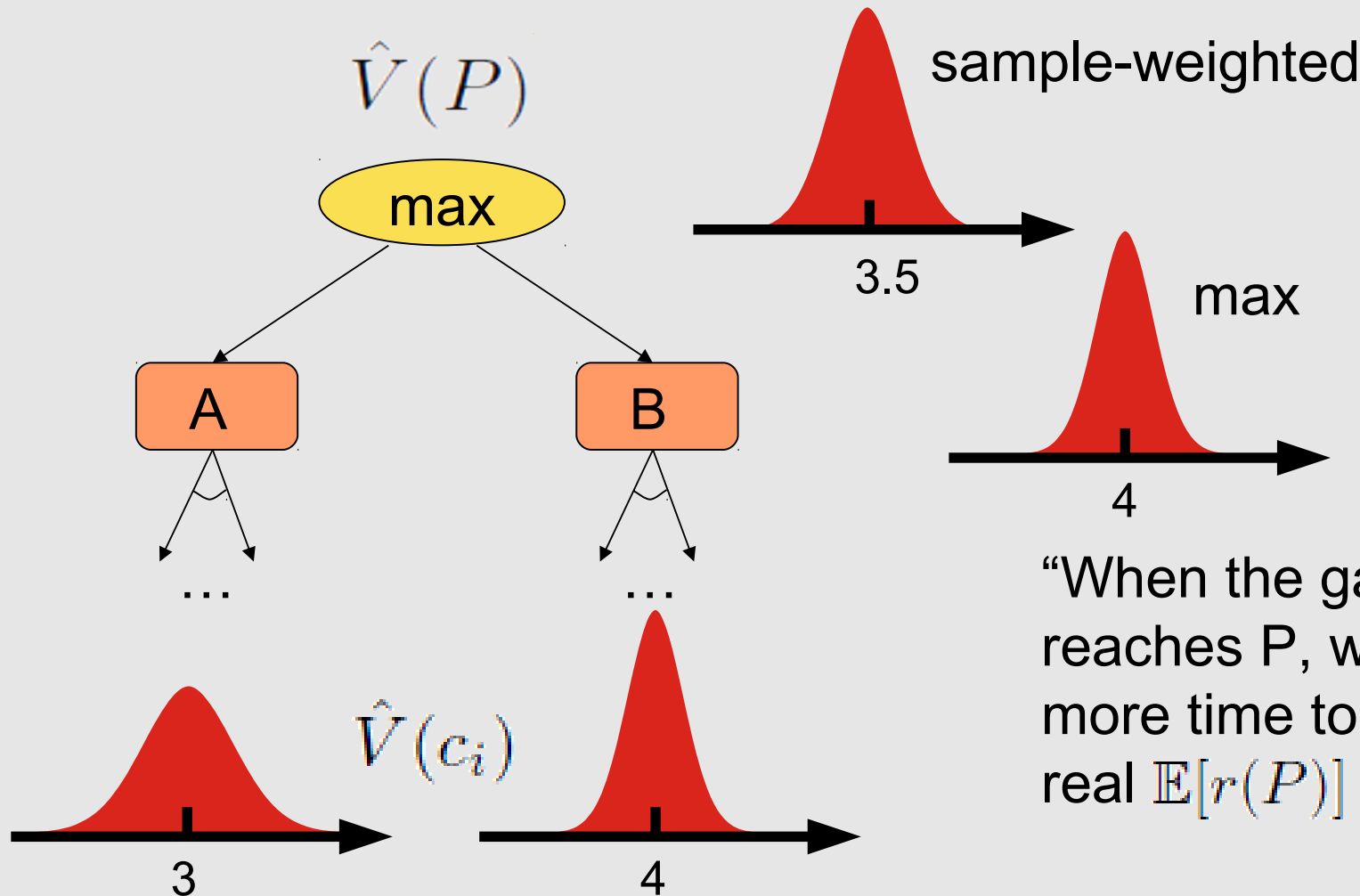


## backpropagation



# ERD max-distribution

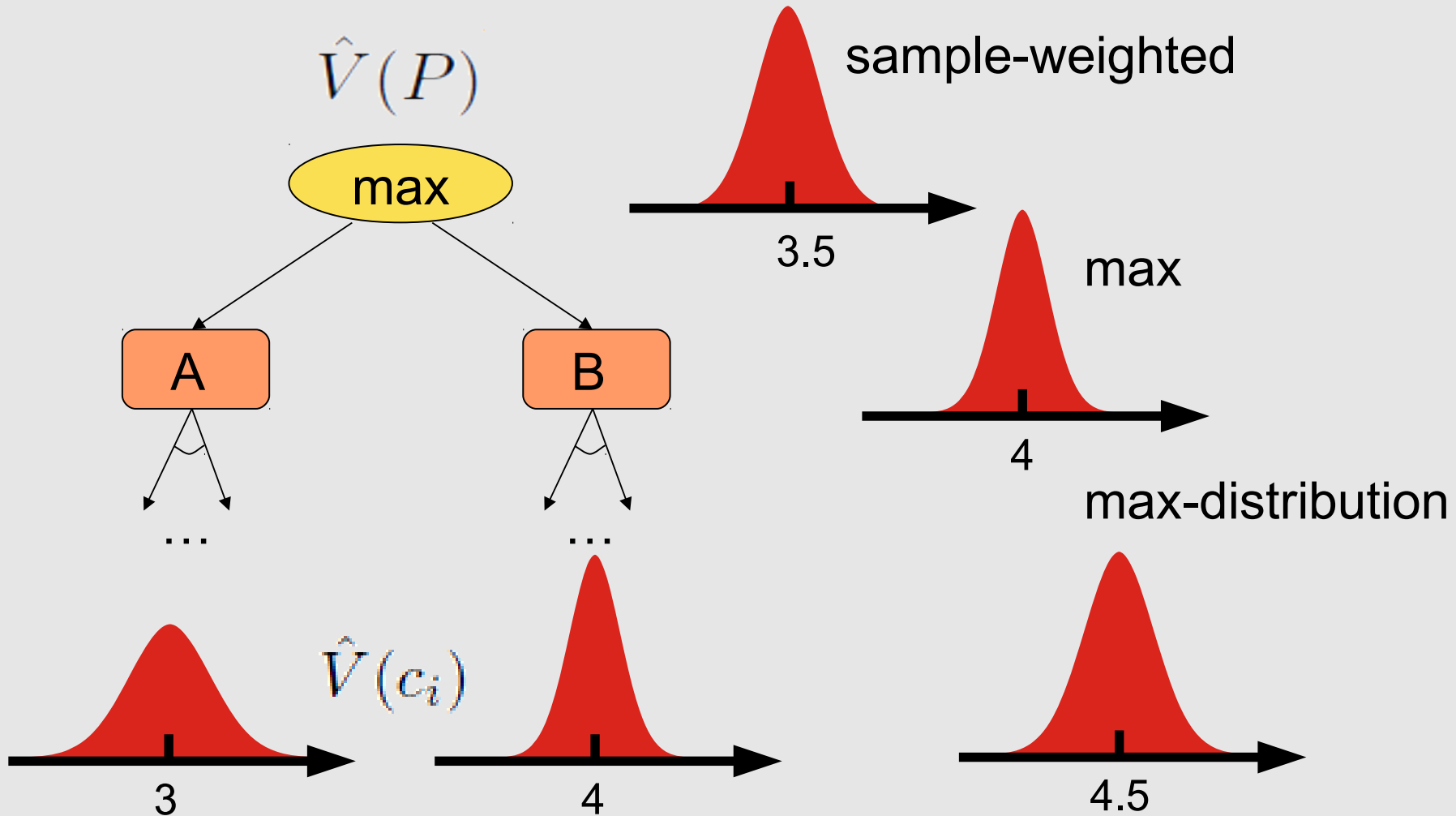
## backpropagation



# ERD max-distribution



## backpropagation



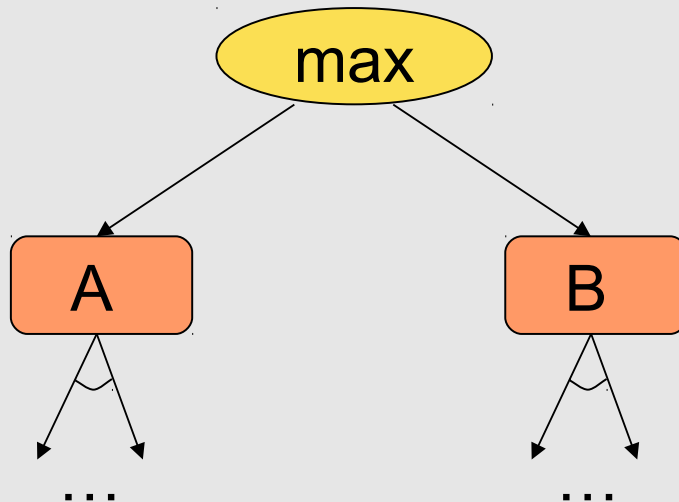
# ERD max-distribution



## backpropagation



$\hat{V}(P)$



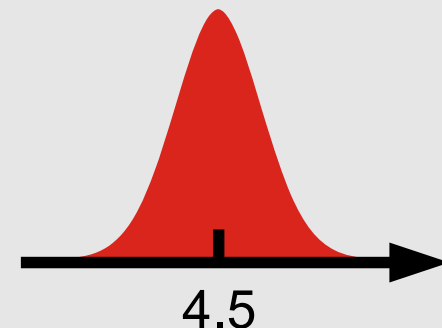
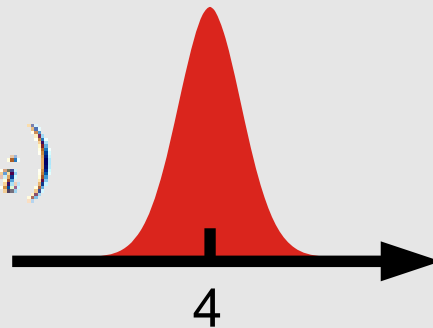
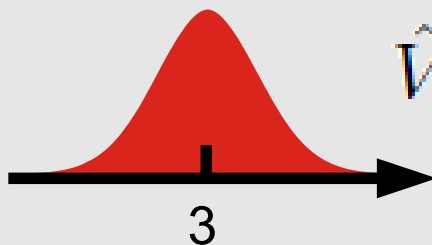
$$P(B < 4) = 0.5 \quad P(B > 4) = 0.5$$

$$P(A < 4) = 0.8 \quad P(A > 4) = 0.2$$

	A < 4	A > 4
B < 4	0.8 * 0.5	0.2 * 0.5
B > 4	0.8 * 0.5	0.2 * 0.5

$$P(\max(A, B) > 4) = 0.6 > 0.5$$

$\hat{V}(c_i)$

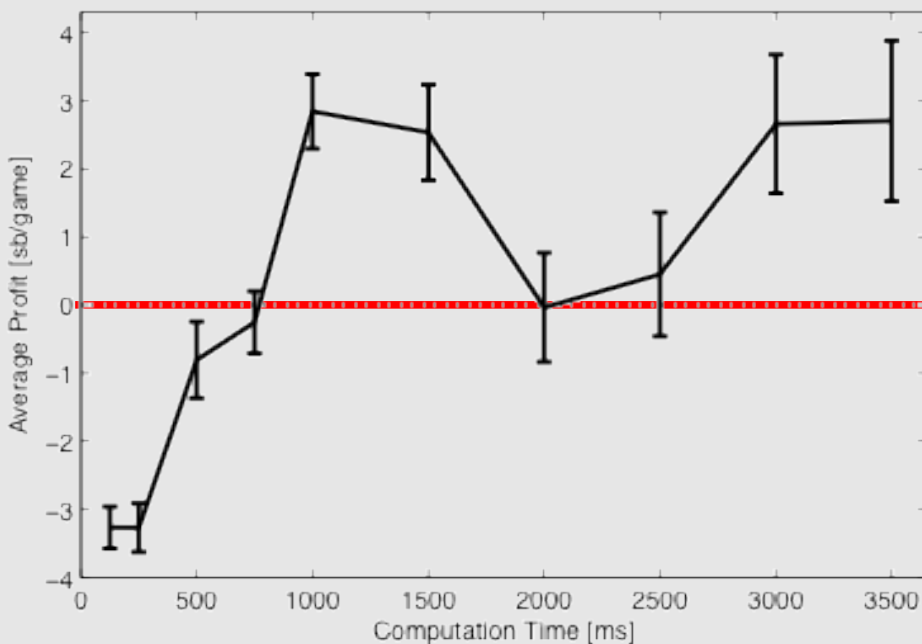


# Experiments



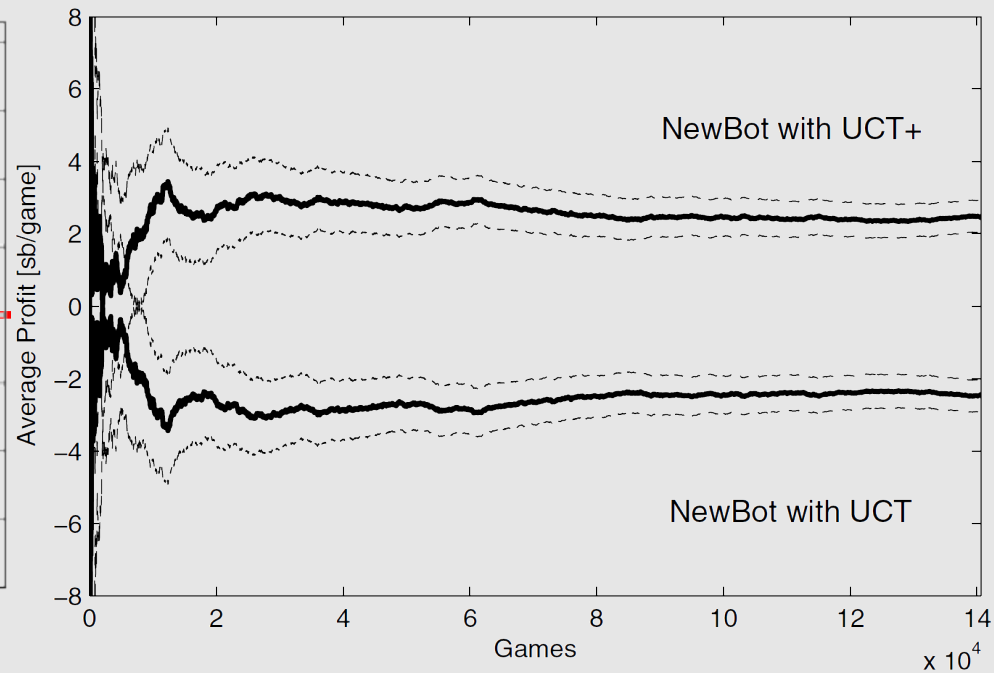
## ! 2\*MCTS

- ! Max-distribution
- ! Sample-weighted



## ! 2\*MCTS

- ! UCT+ (stddev)
- ! UCT



# Outline



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    - ! Online learning
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- ! Conclusion

# Dealing with continuous actions

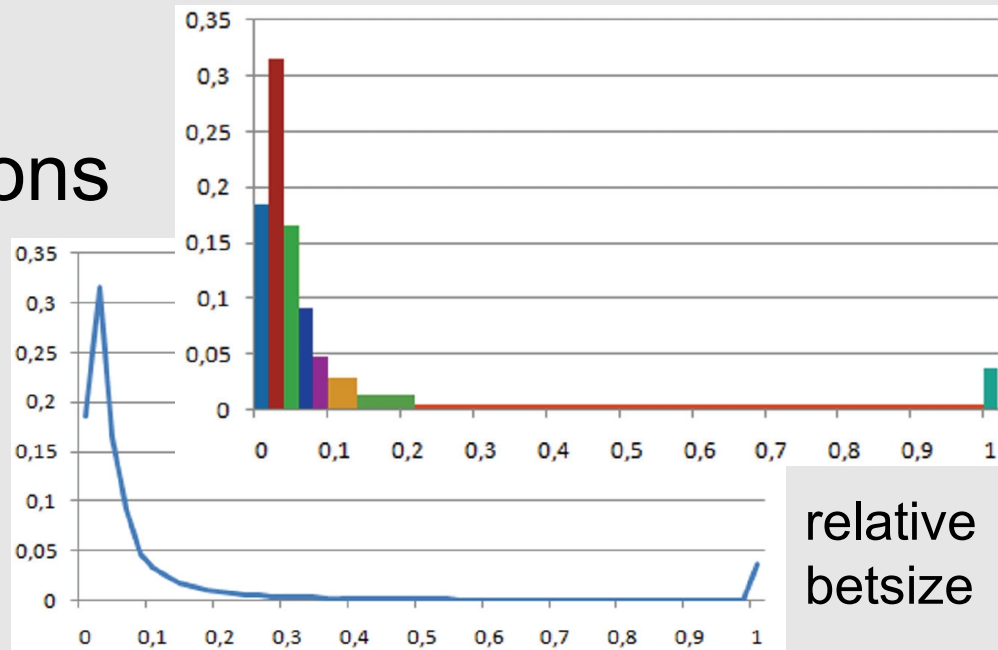


- ! Sample discrete actions

- ! Progressive unpruning [Chaslot08]  
(ignores smoothness of EV function)

- ! ...

- ! Tree learning search (work in progress)



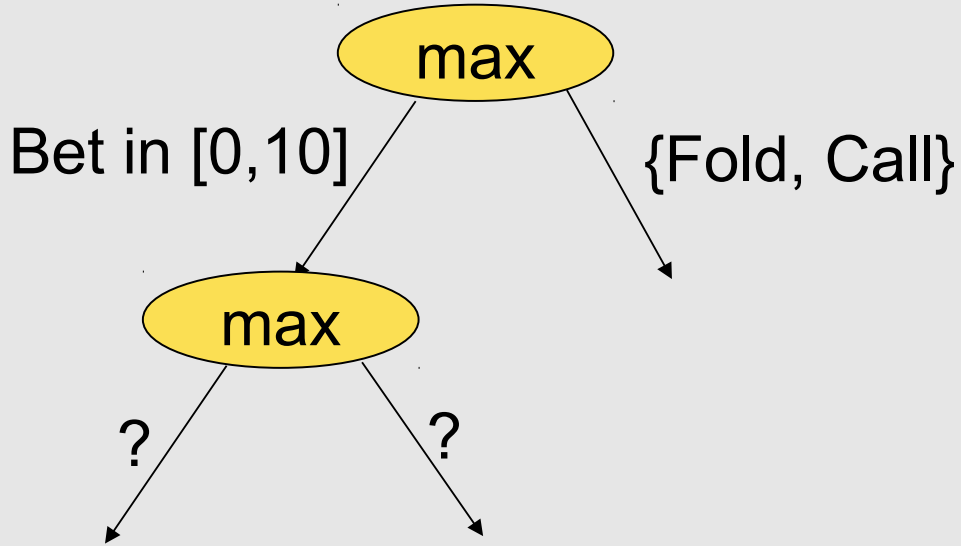


# Tree learning search

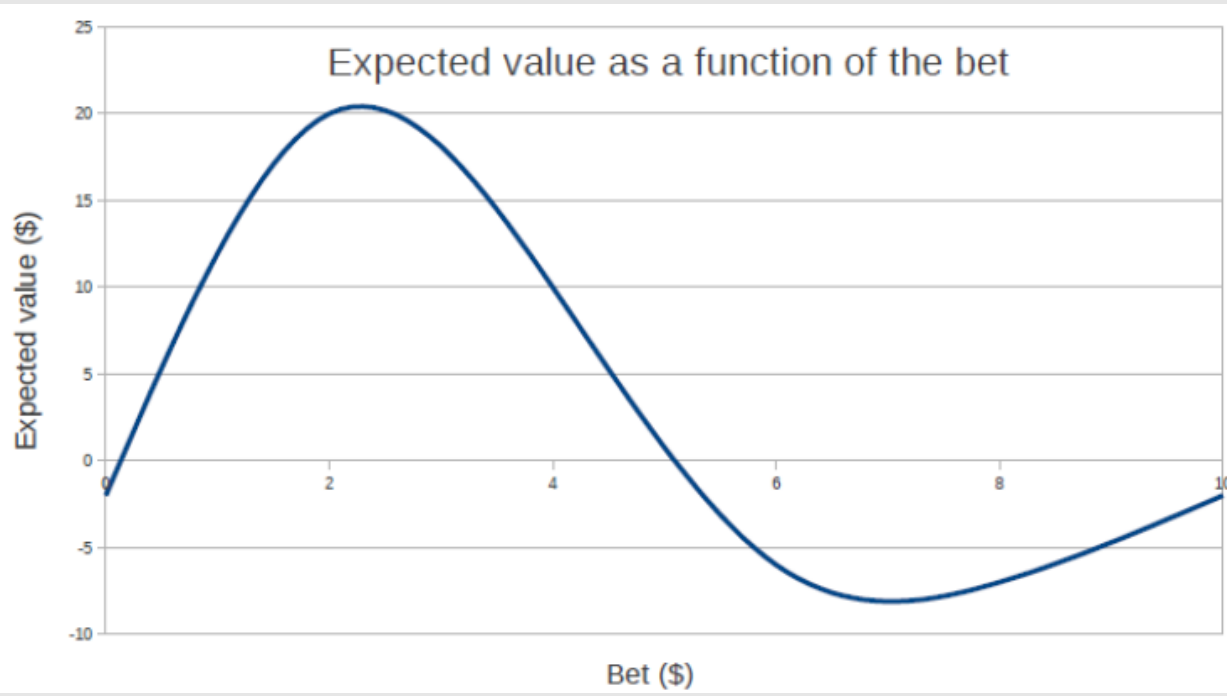
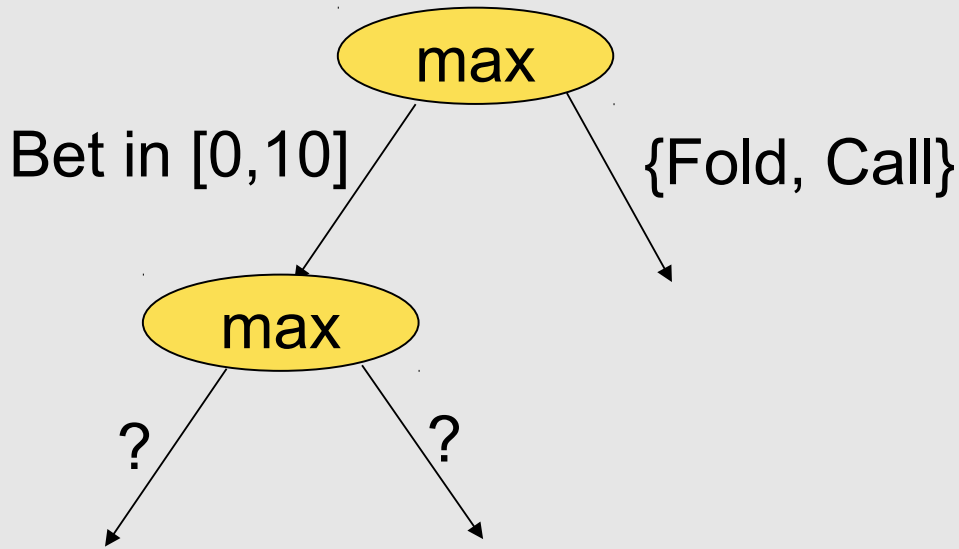


- ! Based on regression tree induction from ***data streams***
  - ! training examples arrive ***quickly***
  - ! nodes ***split*** when significant reduction in stddev
  - ! training examples are immediately ***forgotten***
- ! Edges in TLS tree are not actions, but ***sets of actions***, e.g., (raise in [2,40]), (fold or call)
- ! MCTS provides a ***stream*** of (action, EV) examples
- ! Split action sets to reduce stddev of EV (when significant)

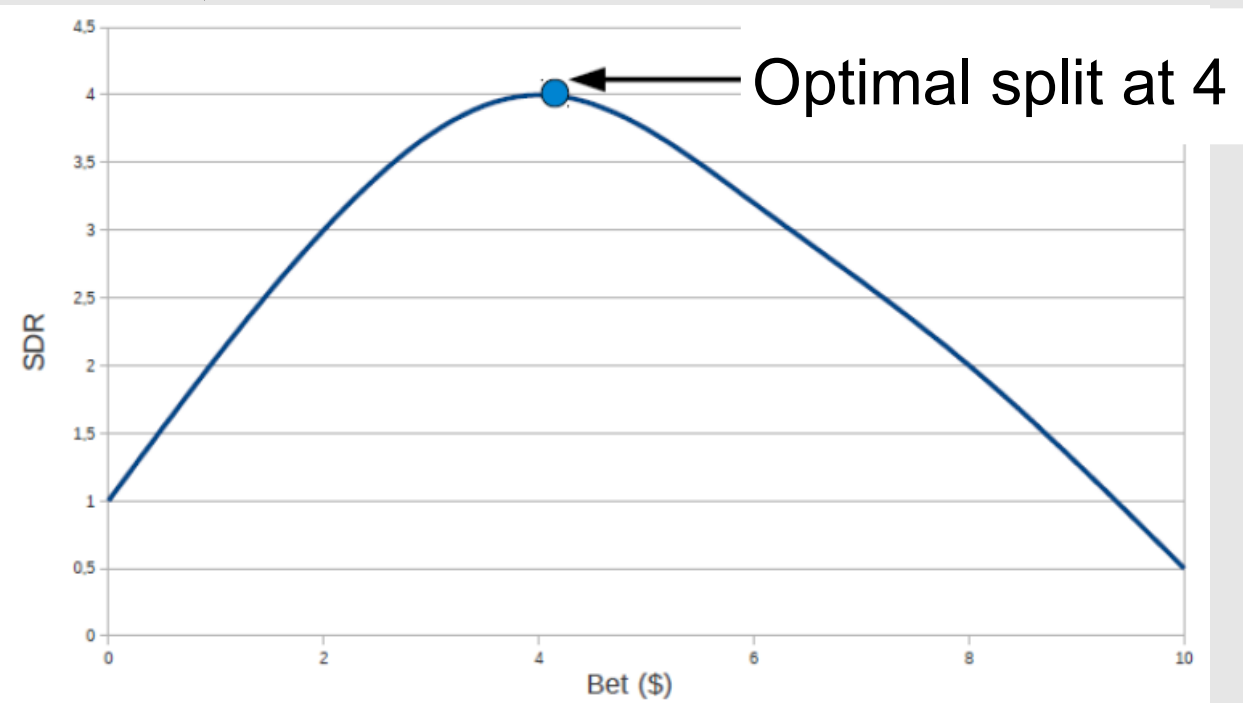
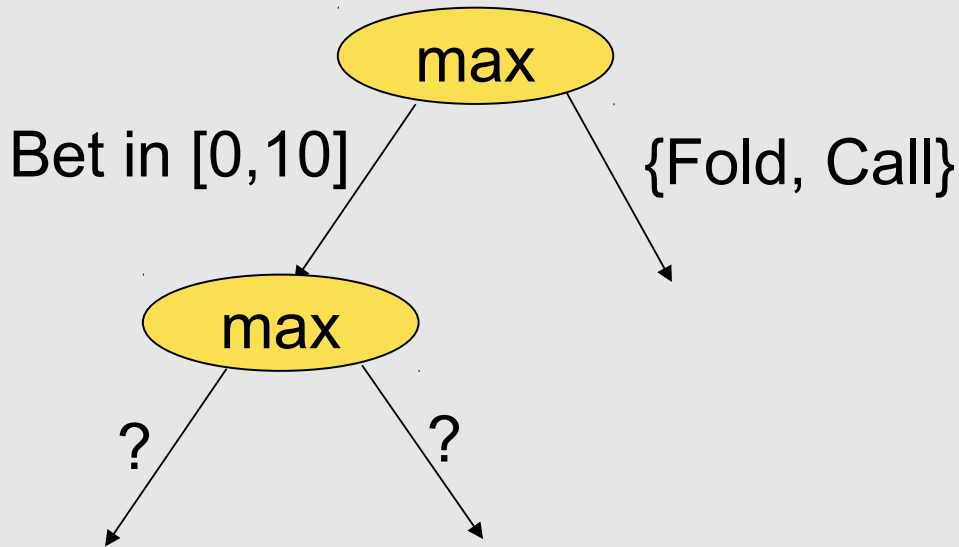
# Tree learning search



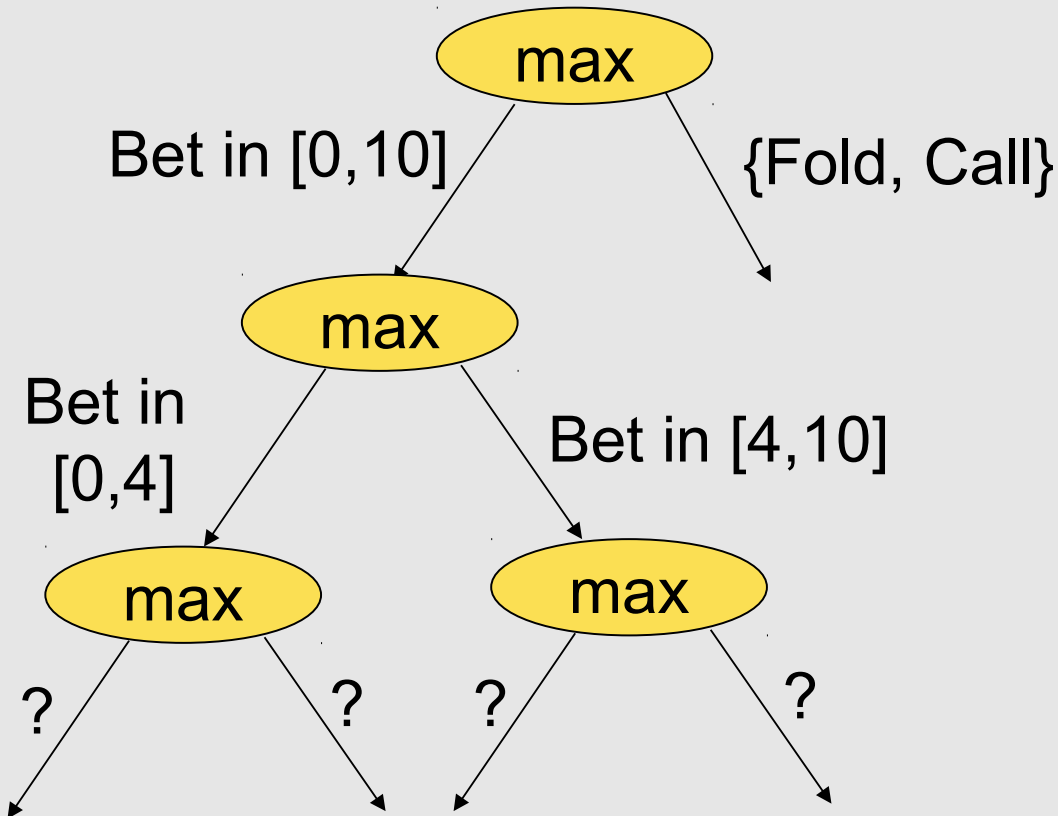
# Tree learning search



# Tree learning search



# Tree learning search



# Tree learning search



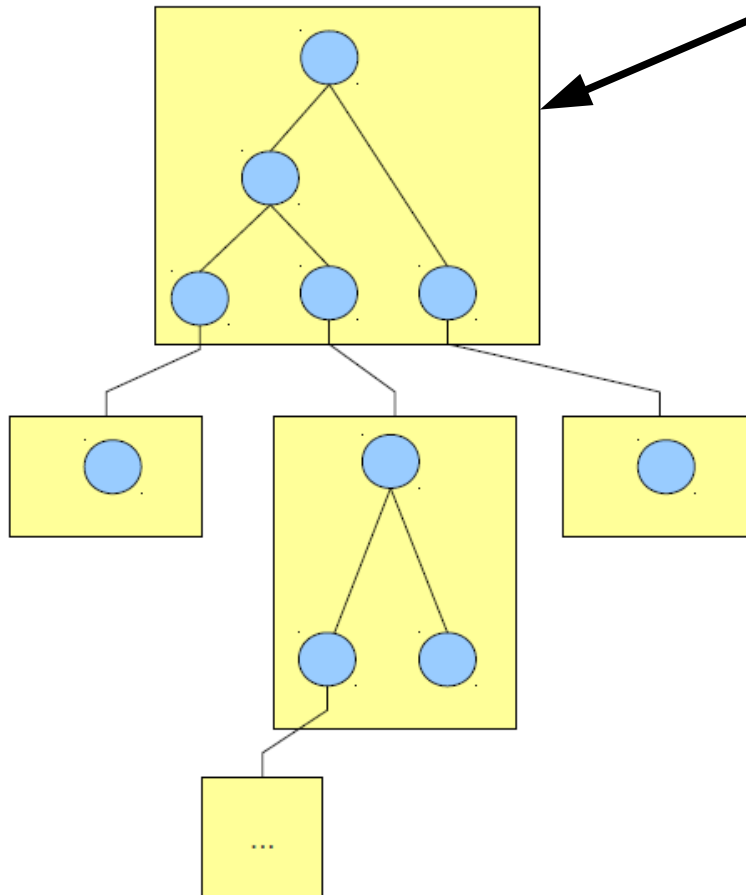
P1

one action of P1

one action of P2

P2

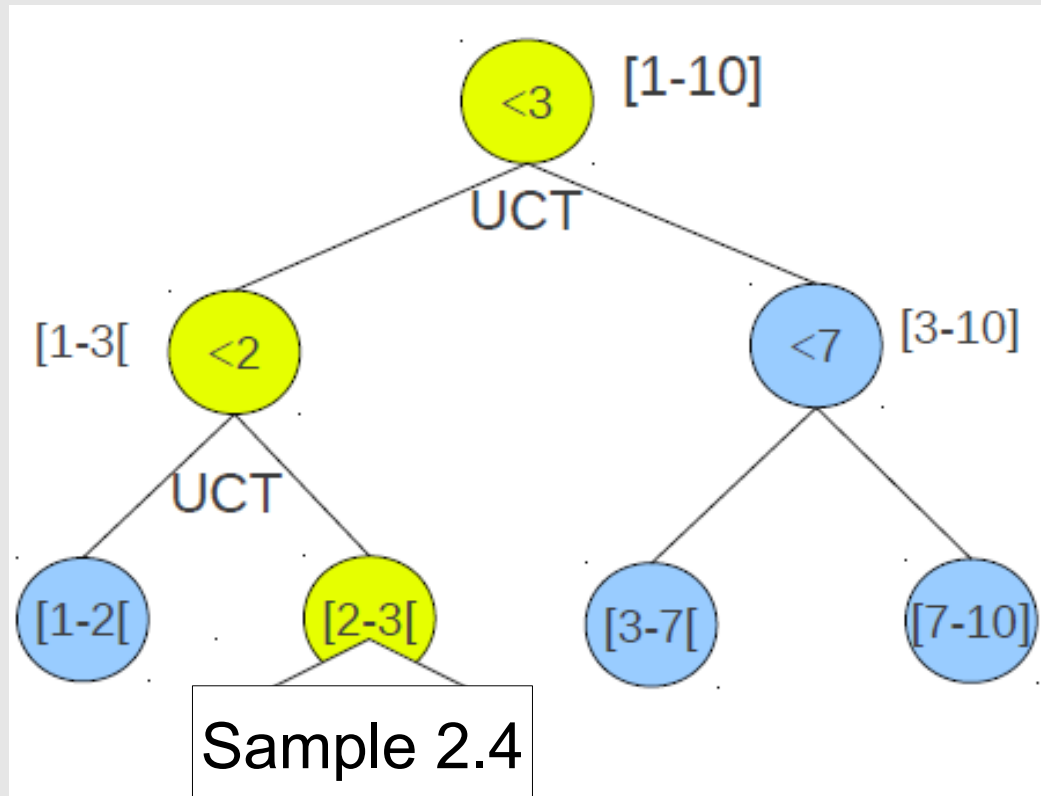
P3



# Selection Phase



P1

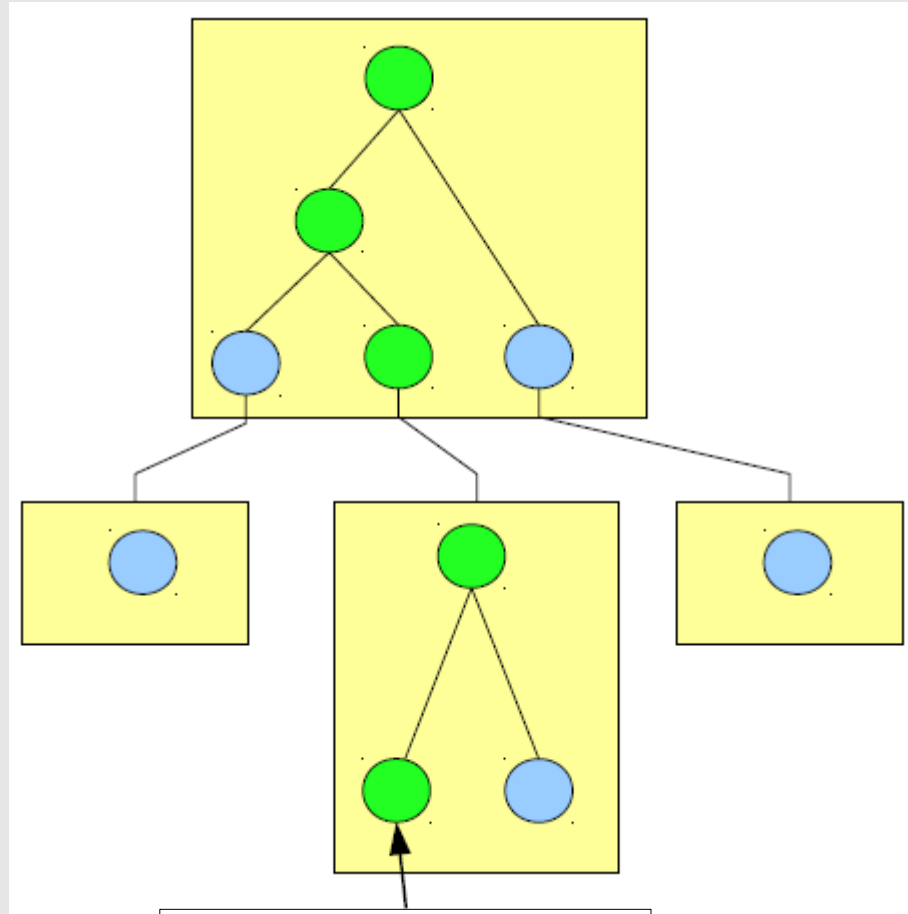


Each node has EV estimate, which generalizes over actions

# Expansion



P1



P2

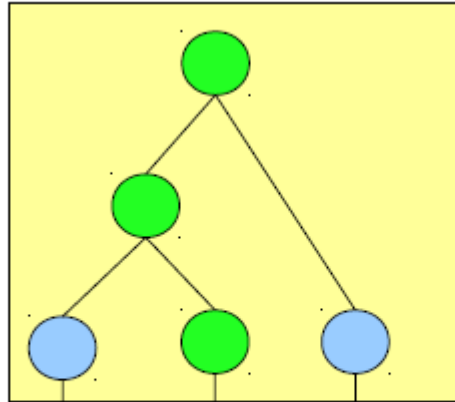
Selected Node



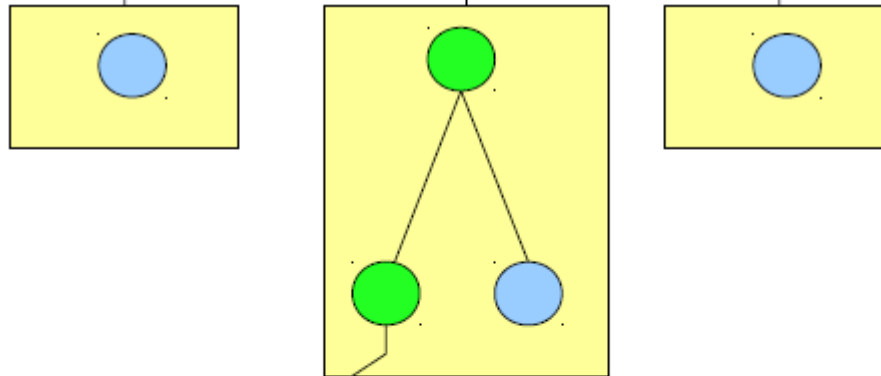
# Expansion



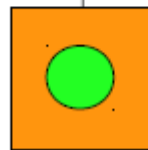
P1



P2



P3

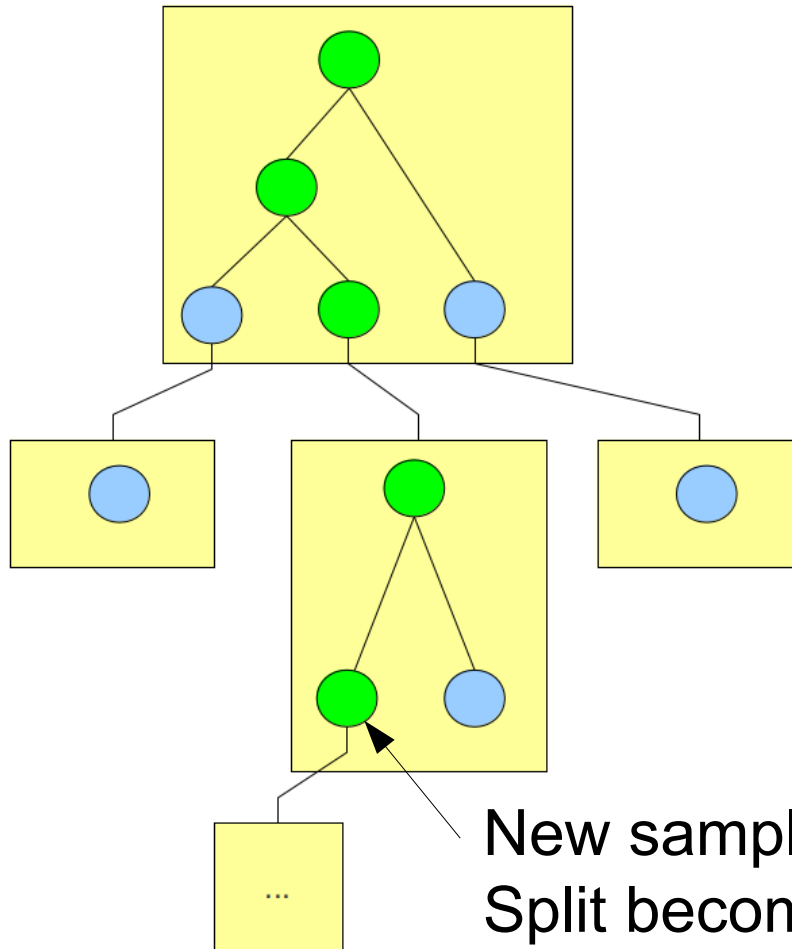


Expanded node  
Represents any action of P3

# Backpropagation



P1



P2

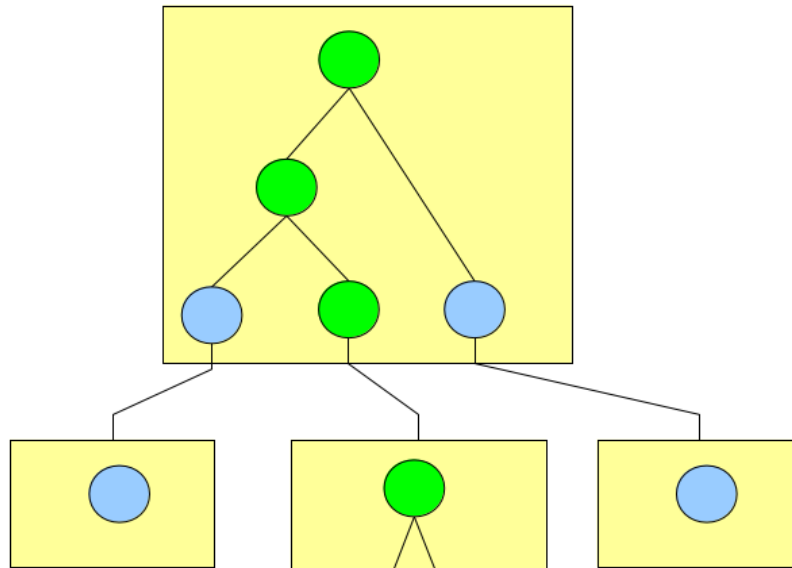
P3

New sample;  
Split becomes  
significant

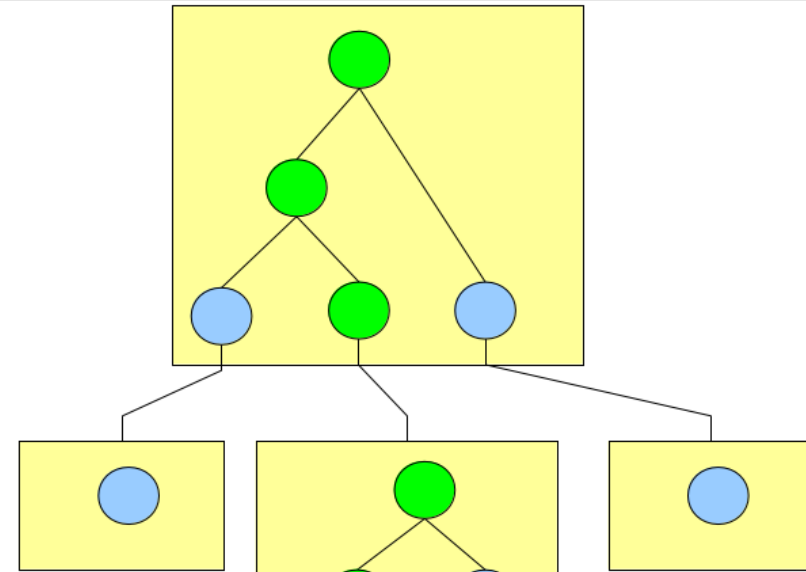
# Backpropagation



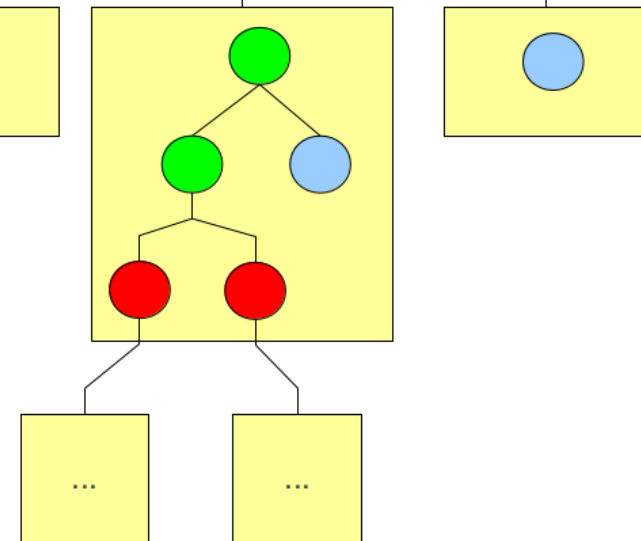
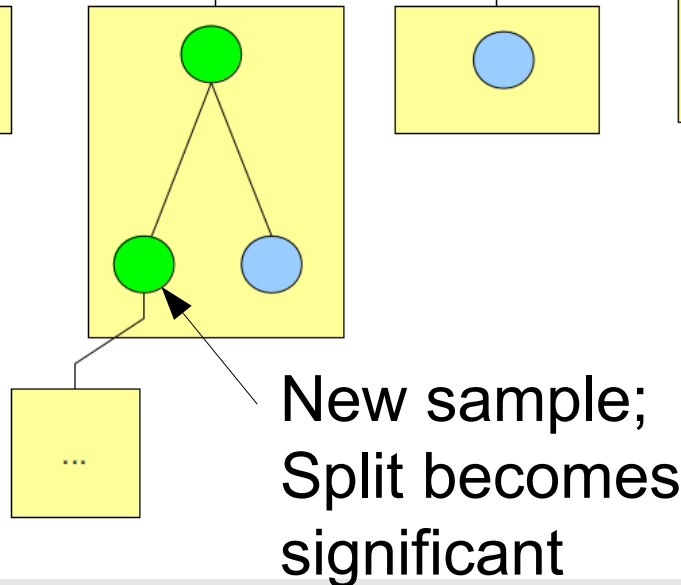
P1



P2



P3



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- ! Conclusion

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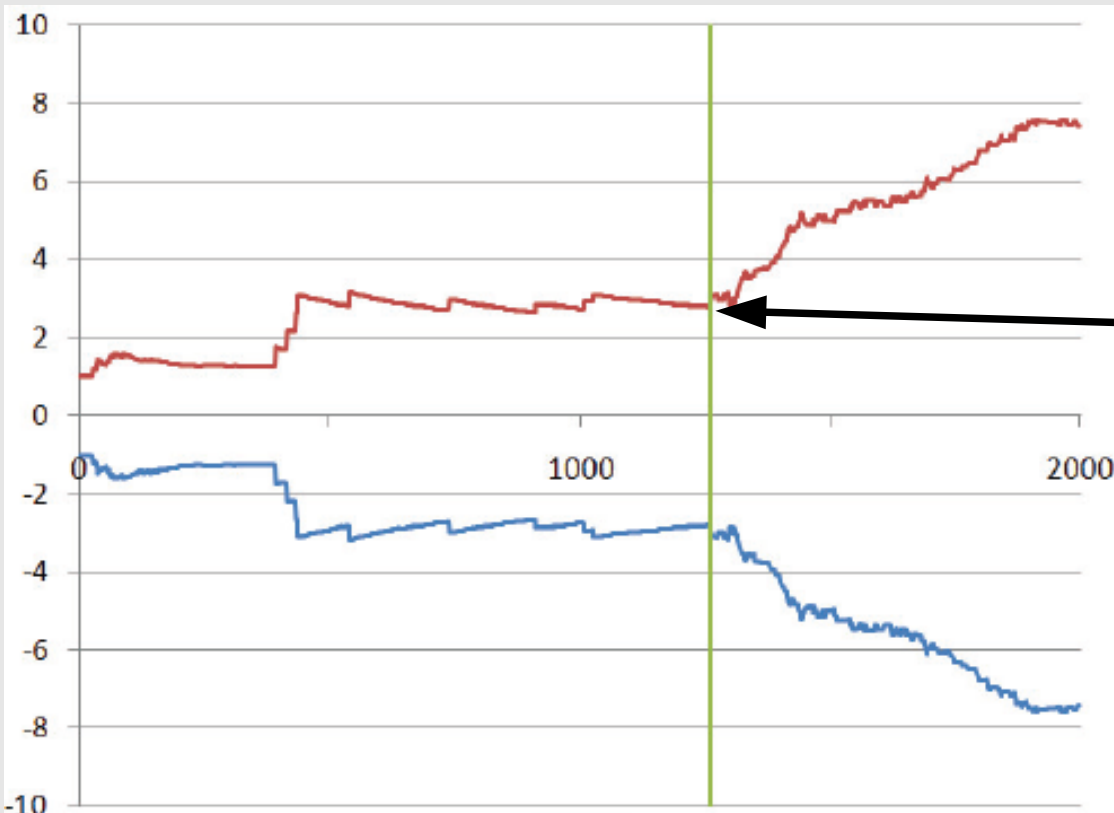


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# Online learning of opponent model



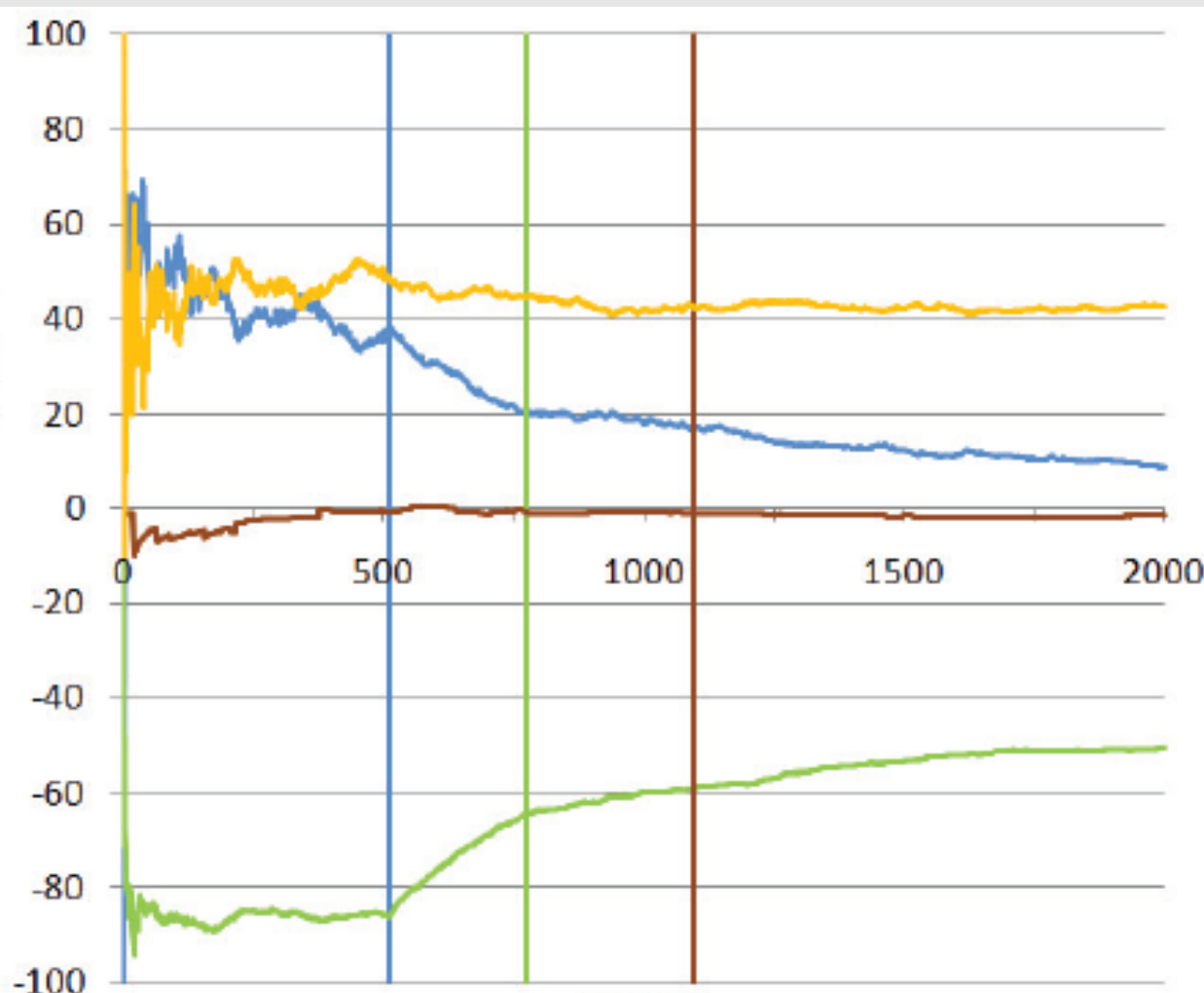
- ! Start from (safe) model of general opponent
- ! Exploit weaknesses of specific opponent



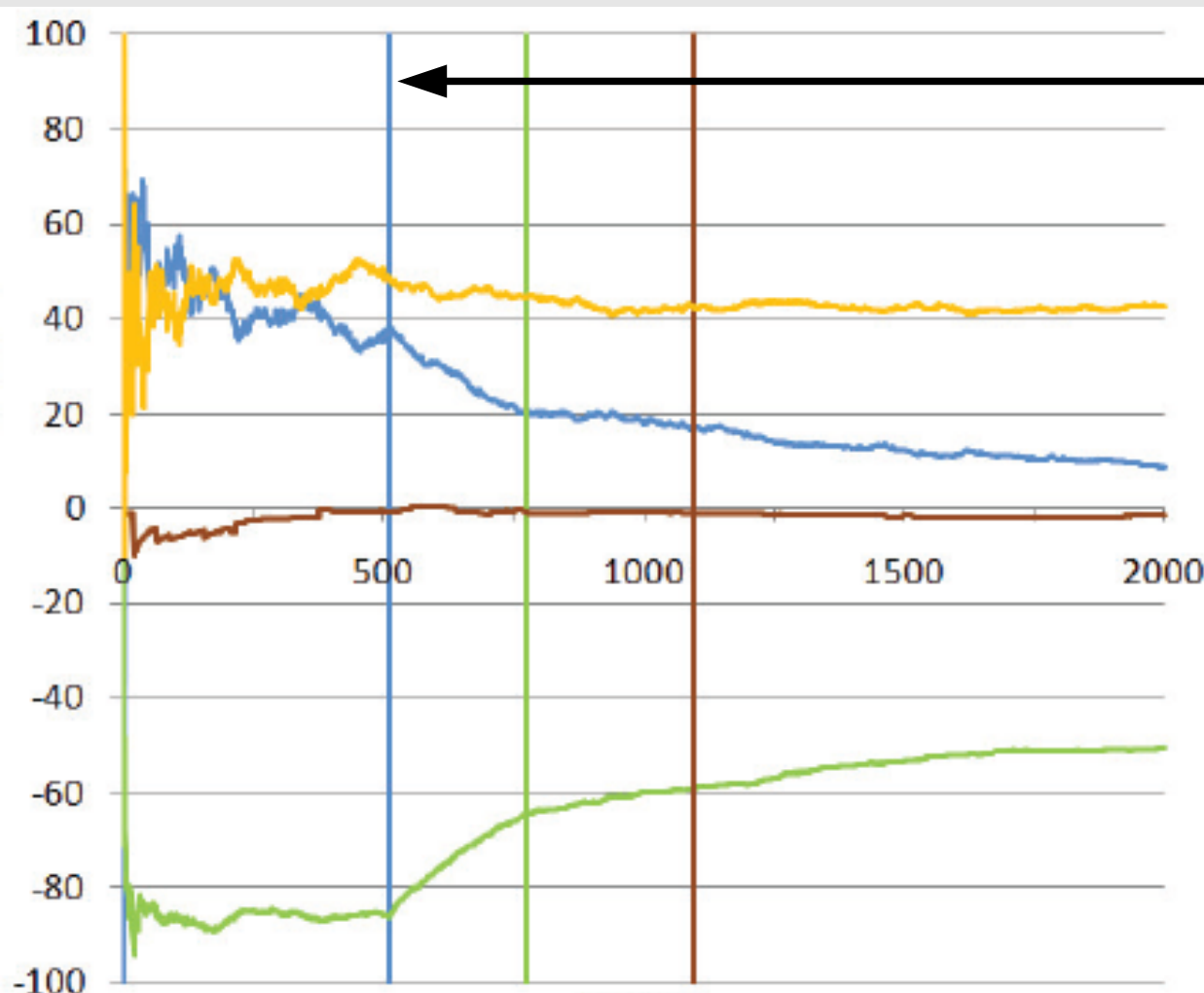
Start to learn model  
of specific opponent

(exploration of  
opponent behavior)

# Multi-agent interaction



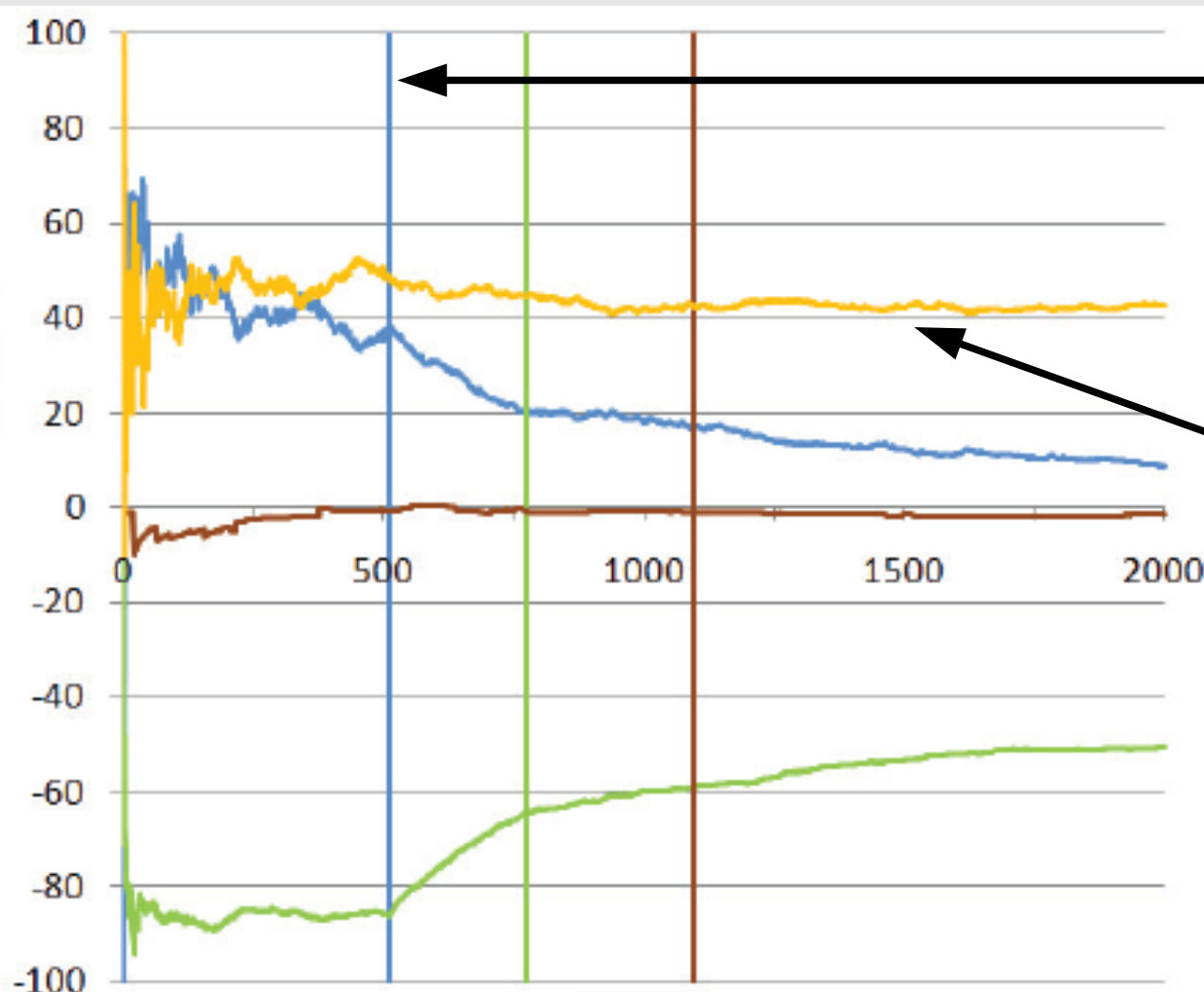
# Multi-agent interaction



Yellow learns model  
for Blue and  
changes strategy



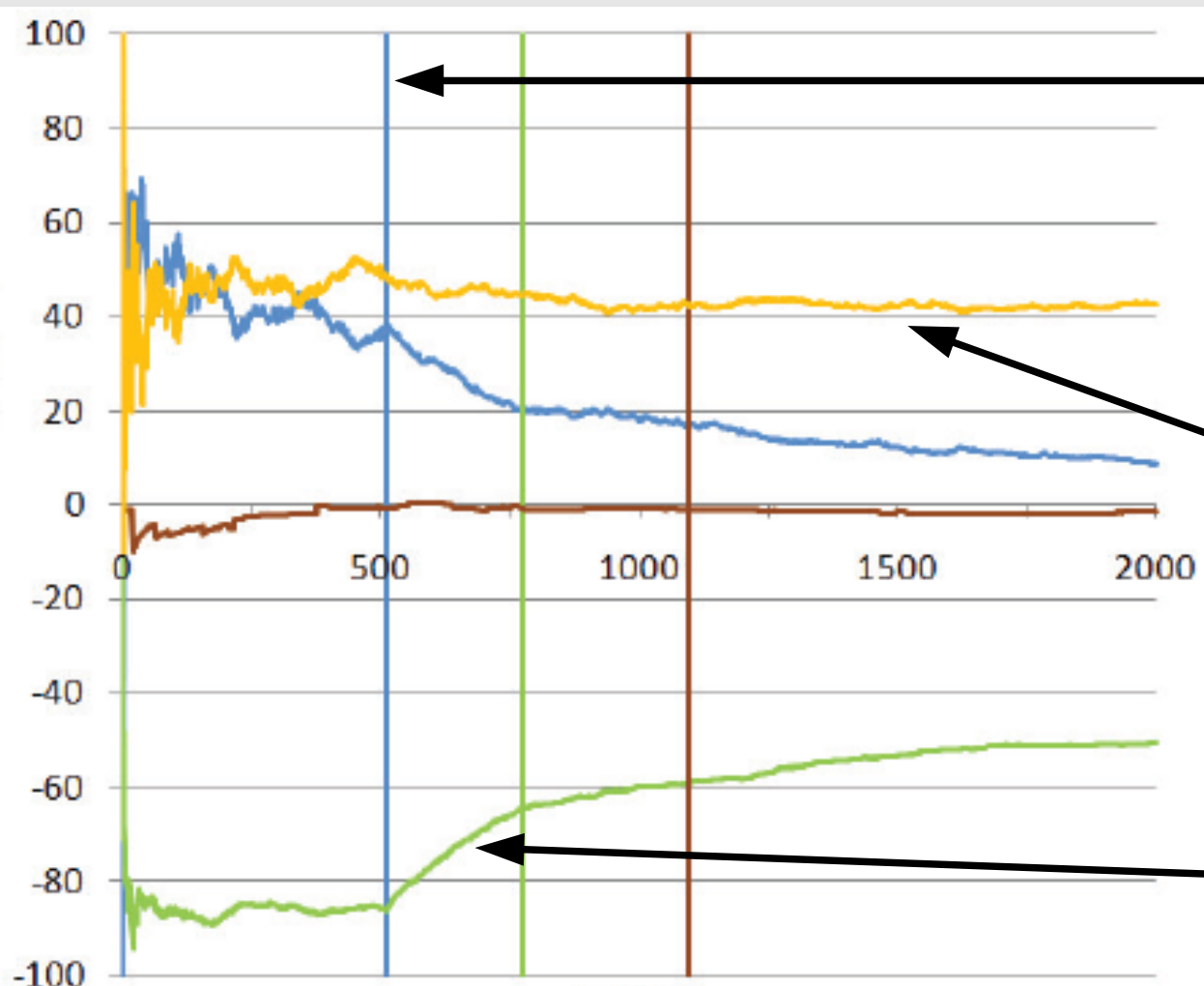
# Multi-agent interaction



Yellow learns model for Blue and changes strategy

Yellow doesn't profit!

# Multi-agent interaction



Yellow learns model for Blue and changes strategy

Yellow doesn't profit!

Green profits without changing strategy!!

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# Concept drift



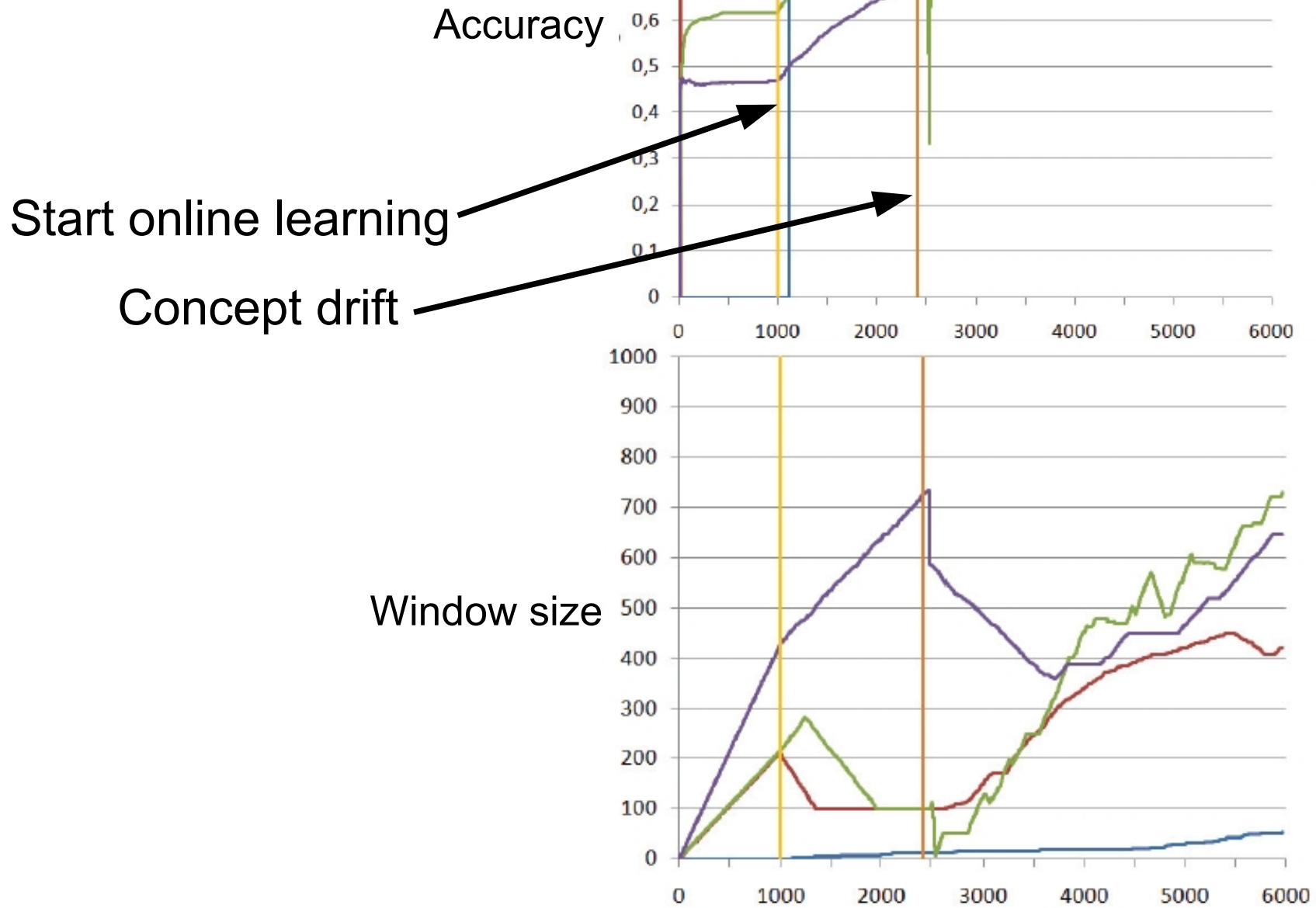
- ! While learning from a stream, the training examples in the stream change
  - ! In opponent model: changing strategy
- ! “***Changing gears*** is not just about bluffing, it's about changing strategy to achieve a goal.”
- ! Learning with concept drift
  - ! ***adapt*** quickly to changes
  - ! yet ***robust*** to noise
  - ! (recognize recurrent concepts)

# Basic approach to concept drift



- ! Maintain a window of training examples
  - ! large enough to learn
  - ! small enough to adapt quickly
  - ! without 'old' concepts
- ! Heuristics to adjust window size
  - ! based on FLORA2 framework [Widmer92]

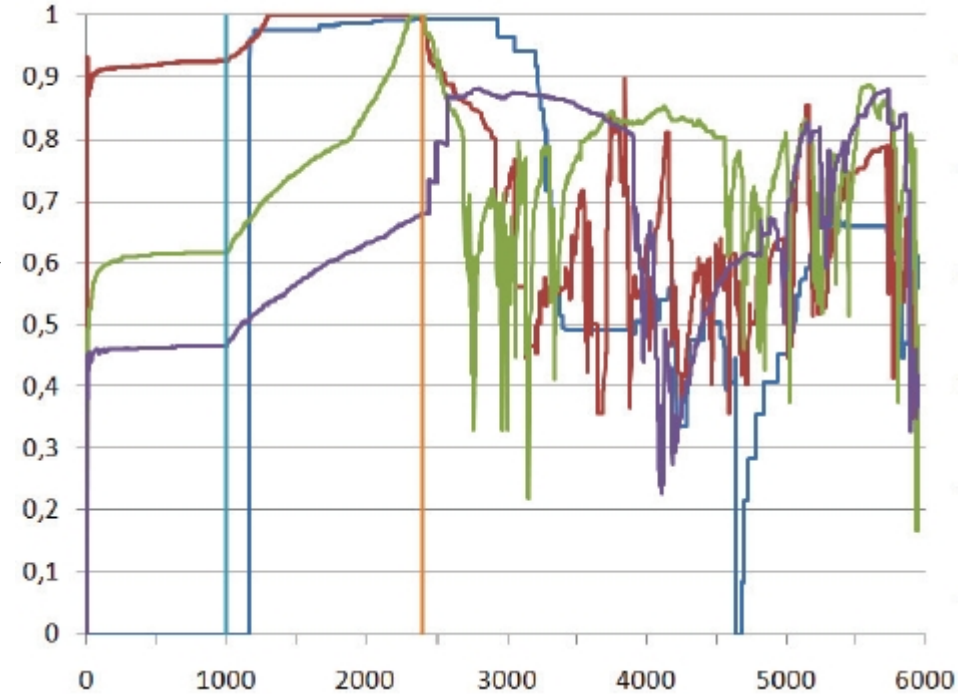
# 4 components of a single opponent model



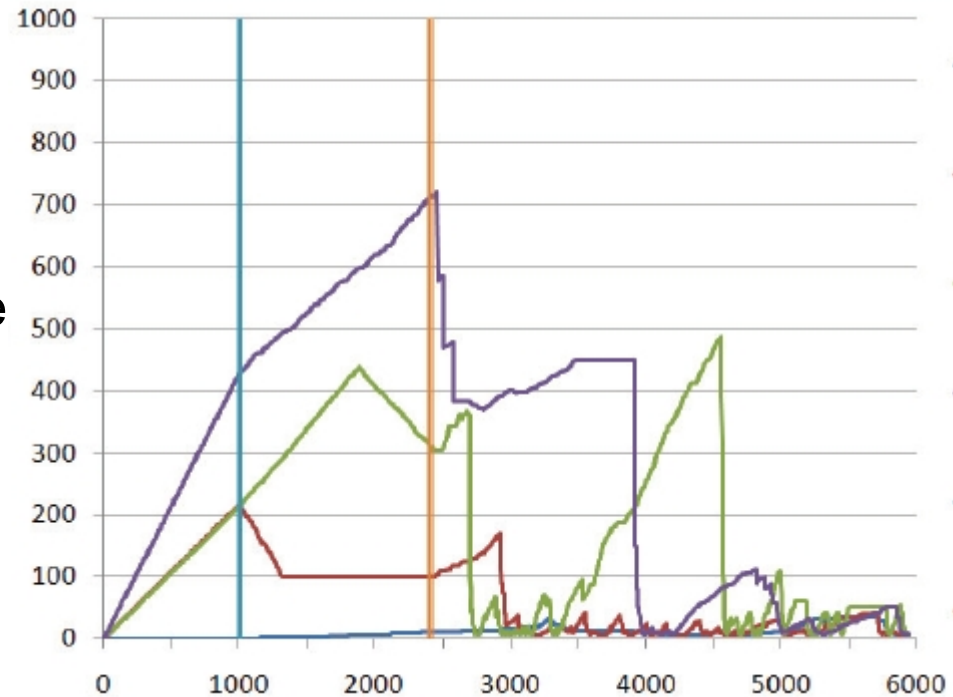
Bad parameters for heuristic



Accuracy



Window size



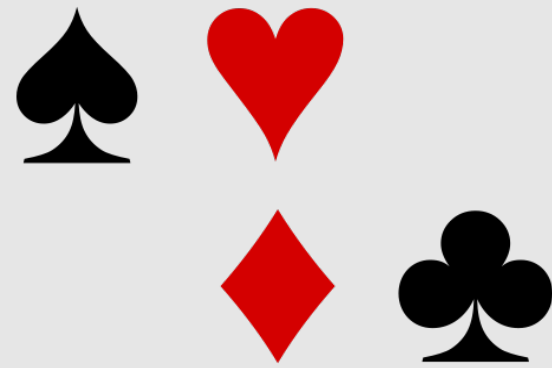
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# Conclusions



! First exploitive poker bot for

- ! *No-limit* Holdem
- ! > 2 players

! Apply in other games

- ! backgammon
- ! computational pool
- ! ...

! Challenge for **MCTS**

- ! games with uncertainty
- ! continuous action space

! Challenge for **ML**

- ! online learning
- ! concept drift
- ! (relational learning)



**Thanks for listening!**

